Semantic vs Syntactic Properties of Graph Polynomials, I:

On the Location of Roots of Graph Polynomials

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Partially joint work with E.V. Ravve and N.K. Blanchard

Graph polynomial project: http://www.cs.technion.ac.il/~janos/RESEARCH/gp-homepage.html

File:t-title 1

References

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 On the Location of Roots of Graph Polynomials
 Special issue of the Erdős Centennial
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- Johann A. Makowsky, Elena V. Ravve, Nicolas K. Blanchard
 On the location of roots of graph polynomials
 European Journal of Combinatorics, Volume 41 (2014), Pages 1-19

File:t-title 2

Overview

- Semantic properties of graph polynomials, 4
- Prominent graph polynomials, 14
- Definability of graph polynomials in Second Order Logic SOL, 20
- Roots of graph polynomials: Many examples, 28
 Spectral graph theory, Chromatic polynomial, Matching polynomials,
 Independence polynomial, Edge-cover polynomial, Domination polynomial
- Roots of graph polynomials: Our results, 41
- Proofs of the theorems, 47
- Conclusion: What did we learn?, 51
- Thanks

Semantic Properties of Graph Polynomials

Graph polynomials

Let \mathcal{R} be a (polynomial) ring.

A function $P: \mathcal{G} \to \mathcal{R}$ is a

graph parameter

if for any two isomorphic graphs $G_1, G_2 \in \mathcal{G}$ we have $P(G_1) = P(G_2)$.

It is a

graph polynomial

if for each $G \in \mathcal{G}$ it is a polynomial.

In this lecture we study univariate graph polynomials P with $\mathcal{R} = \mathbb{Z}[X]$ or $\mathbb{C}[X]$.

A complex number $z \in \mathbb{C}$ is a P-root if there is a graph $G \in \mathcal{G}$ such that P(G,z)=0.

Similar graphs and similarity functions

Two graphs G_1, G_2 are similar if they have the same number of vertices, edges and connected components, i.e.,

- $|V(G_1)| = n(G_1) = n(G_2) = |V(G_2)|$,
- $|E(G_1)| = m(G_1) = m(G_2) = |E(G_2)|$, and
- $k(G_1) = k(G_2)$.

A graph parameter or graph polynomial is a similarity function if it is invariant and similarity.

- (i) The nullity $\nu(G) = m(G) n(G) + k(G)$ and the rank $\rho(G) = n(G) k(G)$ of a graph G are similarity polynomials with integer coefficients.
- (ii) Similarity polynomials can be formed inductively starting with similarity functions f(G) not involving indeterminates, and monomials of the form $X^{g(G)}$ where X is an indeterminate and g(G) is a similarity function not involving indeterminates. One then closes under pointwise addition, subtraction, multiplication and substitution of indeterminates X by similarity polynomials.

Distinctive power of graph polynomials, I

Two graph polynomials are usually compared via their distinctive power.

A graph polynomial Q(G,X) is less distinctive than P(G,Y), $Q \leq P$, if for every two similar graphs G_1 and G_2

$$P(G_1, X) = P(G_2, X)$$
 implies $Q(G_1, Y) = Q(G_2, Y)$.

We also say the P(G; X) determines Q(G; X) if $Q \leq P$.

Two graph polynomials P(G,X) and Q(G,Y) are equivalent in distinctive power (d.p-equivalent) if for every two similar graphs G_1 and G_2

$$P(G_1, X) = P(G_2, X)$$
 iff $Q(G_1, Y) = Q(G_2, Y)$.

The same definition also works for graph parameters and multivariate graph polynomials.

Distinctive power of graph polynomials, II

 \mathbb{C}^{∞} denotes the set of finite sequences of complex numbers. We denote by $cP(G) \in \mathbb{C}^{\infty}$ the sequence of coefficients of P(G,X).

Proposition 1

Two graph polynomials $P(G, X_1, ..., X_r)$ and $Q(G, Y_1, ..., Y_s)$ are equivalent in distinctive power (d.p-equivalent) $(P \sim_{d.p.} Q)$ iff there are two functions $F_1, F_2 : \mathbb{C}^{\infty} \to \mathbb{C}^{\infty}$ such that for every graph G

$$F_1(n(G), m(G), k(G), cP(G)) = cQ(G)$$
 and $F_2(n(G), m(G), k(G), cQ(G)) = cP(G)$

Proposition 1 shows that our definition of equivalence of graph polynomials is mathematically equivalent to the definition proposed by C. Merino and S. Noble in 2009.

Computability

The functions F_1, F_2 in Proposition 1 need not be computable in any sense, even if the coefficients of P(G) and Q(G) are integers.

A graph polynomial P(G; X) with coefficients in a ring \mathcal{R} is computable (in a suitable model of computation for \mathcal{R}) if

- (i) the function $cP:\mathcal{G}\to\bigcup_n\mathcal{R}^n$ computing the coefficients of P(G;X) is computable, and
- (ii) the decision problem, given $s \in \bigcup_n \mathcal{R}^n$ is there a graph with cP(G) = s is decidable.

Theorem 2

Let P(G;X) and Q(G;X) be two computable graph polynomials which are d.p.-equivalent. Then there are F_1, F_2 as in Proposition 1 which are computable.

In this case we say that P(G; X) and Q(G; X) are computably d.p.-equivalent.

Prefactor and subtsitution equivalence, I

• We say that $P(G; \bar{X})$ is prefactor reducible to $Q(G; \bar{X})$ and we write $P(G; \bar{Y}) \leq_{prefactor} Q(G; \bar{X})$

if there are similarity functions

$$f(G; \bar{X}), g_1(G; \bar{X}), \dots, g_r(G; \bar{X})$$

such that

$$P(G; \bar{Y}) = f(G; \bar{X}) \cdot Q(G; g_1(G; \bar{Y}), \dots, g(G; \bar{Y})).$$

- We say that $P(G; \bar{X})$ is substitutions reducible to $Q(G; \bar{X})$, and we write $P(G; \bar{Y}) \leq_{subst} Q(G; \bar{X})$ if $f(G; \bar{X}) = 1$ for all values of \bar{X} .
- $P(G; \bar{X})$ and $Q(G; \bar{X})$ are prefactor (substitution) equivalent if the relationship holds in both directions.

It follows that if $P(G; \bar{X})$ and $Q(G; \bar{X})$ are prefactor (substitution) equivalent then they are computably d.p.-equivalent.

Semantic properties of graph parameters

A semantic property is a class of graph parameters (polynomials) closed under d.p.-equivalence.

Let p(G) be a graph parameter with values in \mathbb{N} , and P(G;X) be a graph polynomial.

- The degree of P(G;X) equals p(G) is not a semantic property of P(G;X). Using Proposition 1 we see that P(G;X) and $P(G;X^2)$ are d.p.-equivalent, but they have different degrees.
- P(G; X) determines p(G) is a semantic property of P(G; X).

Semantic vs syntactic properties of graph polynomials, I

Semantically meaningless properties:

- (i) P(G,X) is monic for each graph G, i.e., the leading coefficient of P(G;X) equals 1.
 - Multiplying each coefficient by a fixed polynomial gives an equivalent graph polynomial.
- (ii) The leading coefficient of P(G,X) equals the number of vertices of G. However, proving that two graphs G_1, G_2 with $P(G_1,X) = P(G_2,X)$ have the same number of vertices is semantically meaningful.
- (iii) The graph polynomials P(G;X) and Q(G;X) coincide on a class \mathcal{C} of graphs, i.e. for all $G \in \mathcal{C}$ we have P(G;X) = Q(G;X).
 - The semantic content of this situation says that if we restrict our graphs to C, then P(G; X) and Q(G; X) have the same distinguishing power.
 - The equality of P(G;X) and Q(G;a)X is a syntactic conincidence or reflects a clever choice in the definitions P(G;X) and Q(G;X).

Semantic vs syntactic properties of graph polynomials, II

Clever choices of can be often achieved.

Let \mathcal{C} be class of finite graphs closed under graph isomorphisms.

Proposition 3

Assume that P(G;X) and Q(G;X) have the same distinguishing power on a class of graphs \mathcal{C} . Then there is $P' \sim_{d.p.} P$ such that the graph polynomials P'(G;X) and Q(G;X) coincide on a class \mathcal{C} of graphs.

If, additionally, C, P(G; X) and Q(G; X) are computable, then P'(G; X) can be made computable, too.

Proposition 3 also holds when we replace computable by definable in SOL, as we shall see later.

Back to overview

Prominent graph polynomials

File:t-matching 14

Spectral graph theory, I

Let G = (V(G), E(G)) be a loopless graph without multiple edges.

- A_G is the adjacency matrix of a graph G.
- D_G is the diagonal matrix with $(D_G)_{i,i} = d(i)$, the degree of the vertex i.
- $L_G = D_G A_G$ is the Laplacian of G.

In spectral graph theory two computable graph polynomials are considered:

ullet The characteristic polynomial $P_A(G;X)$ of G defined as

$$P_A(G;X) = \det(X \cdot \mathbb{I} - A_G)$$

ullet and the Laplacian polynomial $P_L(G;X)$ of G defined as

$$P_L(G;X) = \det(X \cdot \mathbb{I} - L_G)$$

Here I denotes the unit element in the corresponding matrix ring.

Spectral graph theory, II

G and H below are similar.



We have

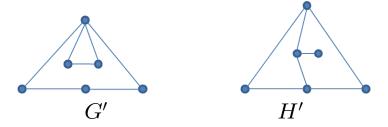
$$P_A(G;X) = P_A(H;X) = (X-1)(X+1)^2(X^3-X^2-5X+1),$$

but G has eight spanning trees, and H has six.

Therefore, $P_L(G; X) \neq P_L(H; X)$, as one can compute the number of spanning trees from $P_L(G; X)$.

Spectral graph theory, III

On the other hand, the graphs below G' and H' are similar, but G' is not bipartite, whereas, H' is.



As P_A determines bipartiteness, we have $P_A(H';X) \neq P_A(G',X)$, but one can easily check that $P_L(H';X) = P_L(G';X)$.

Conclusion:

The characteristic polynomial and the Laplacian polynomial are d.p.-incomparable. However, if restricted to k-regular graphs, they are d.p.-eqivalent.

File:t-matching 17

Matching polynomials, I

There are two versions of the univariate matching polynomial: The matching defect polynomial (or acyclic polynomial)

$$dm(G; X) = \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} (-1)^k m_k(G) X^{n-2k},$$

and the matching generating polynomial

$$gm(G;X) = \sum_{k=0}^{n} m_k(G)X^k$$

The relationship between the two is given by

$$dm(G;X) = \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} (-1)^k m_k(G) X^{n-2k} = X^n \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} (-1)^k m_k(G) X^{-2k} =$$

and

$$= X^{n} \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} m_{k}(G)((-1) \cdot X^{-2})^{k} = X^{n} \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} m_{k}(G)(-X^{-2})^{k} = X^{n} gm(G; (-X^{-2}))$$

The matching polynomials, II

It follows that

- Both matching polynomials are computable.
- \bullet gm and dm are d.p.-equivalent.
- However, gm(G; X) is invariant under addition or removal of isolated vertices, whereas dm(G; X) counts them.

Furthermore we have

Theorem 4 (Godsil and Gutmann) A graph G is a forest iff $dm(G, X) = P_A(G; X)$.

This is a syntactic theorem. One cannot replace dm(G; X) by gm(G; X).

It holds for $P_L(G; X)$ only if one restricts it to k-regular forests.

Back to overview

File:t-matching 19

Definability of Graph Polynomials

in Second Order Logic SOL

Graph polynomials definable in Second Order Logic SOL, I

There are too many d.p.-equivalent graph polynomials.

For example, let $f: \mathbb{N} \to \mathbb{N}$ and $g: \mathbb{N} \to \mathbb{N}$ be two injective functions and

let $P(G,X) = \sum_{i} a_i(G)X^i$ a graph polynomial.

Then $Q(G,X) = \sum_{i} a_{f(i)(G)} X^{g(i)}$ is equivalent to P(G,X).

SOL-definable generating functions:

Let $\phi(U)$ be an SOL-formula in the language of graphs with a free relation variable U. Let

$$a_i(G) = \mid \{U \subseteq V : (G, U) \models \phi(U) \text{ and } |U| = i\} \mid$$

be uniformly defined numeric graph parameters.

Then

$$\sum_{i} a_i(G)X^i = \sum_{U:\phi(u)} X^{|U|}$$

is a the simplest form of an SOL-definable graph polynomial.

Graph polynomials definable in Second Order Logic SOL, II

We can form many d.p.-equivalent graph polynomials such as

$$\sum_{i} a_i(G)X^i = \sum_{U:\phi(u)} X^{|U|} \tag{1}$$

$$\sum_{i} a_{i}(G)(-1)^{i} X^{i} = \sum_{U:\phi(u)} (-1)^{|U|} X^{|U|}$$
(2)

$$\sum_{i} a_{i}(G) X^{|V(G)|-i} = \sum_{U:\phi(u)} X^{|V(G)-U|}$$
(3)

$$\sum_{i} a_{i}(G) {X \choose i} = \sum_{U:\phi(u)} {X \choose |U|}$$
(4)

$$\sum_{i} a_i(G) X^{\underline{i}} = \sum_{U:\phi(u)} X^{|U|} \tag{5}$$

Simple SOL-definable graph polynomials

The graph polynomial $dm(G;X) = \sum_i m_i(G) \cdot X^i$, can be written also as

$$dm(G; X) = \sum_{M \subseteq E(G)} \prod_{e \in E} X$$

where M ranges over all matchings of G.

To be a matching is definable by a formula $\phi(I)$ of Second Order Logic SOL

A simple SOL-definable graph polynomial P(G,X) is a polynomial of the form

$$P(G,X) = \sum_{A \subseteq V(G)^r: \phi(A)} \prod_{v \in A} X$$

where A ranges over all subsets of $V(G)^r$ satisfying $\phi(A)$ and $\phi(A)$ is a SOL-formula.

General SOL-definable graph polynomials

For the general case

- One allows several indeterminates X_1, \ldots, X_t .
- One gives an inductive definition.
- One allows an ordering of the vertices.
- One requires the definition to be **invariant under the ordering**, i.e., different orderings still give the same polynomial.
- This also allows to define the modular counting quantifiers $C_{m,q}$ "there are, modulo q exactly m elements..."

The general case includes the Tutte polynomial, the cover polynomial, and virtually all graph polynomials from the literature.

Graph polynomials definable in Second Order Logic SOL, III

Let P(G,X) be a SOL-definable graph polynomial and let S(G,X) be and SOL-definable similarity function.

Then the following polynomials are SOL-definable and d.p.-equivalent:

- S(G,X) + P(G,X)
- $S(G,X) \cdot P(G,X)$

In the second case S(G; X) is called in the literature a prefactor.

The two matching polynomials are related to each other by a substitution and by a prefactor.

$$dm(G;X) = X^n \cdot gm(G;(-X^{-2}))$$

(Almost) all graph polynomials

from the literature

are SOL-definable!

Back to overview

Computability of SOL-definable graph polynomials

Proposition 5

Every SOL-definable graph polynomial P(G; X) with coefficients in a ring \mathcal{R} is computable in a model of computation suitable for \mathcal{R} .

For a detailed discussion of the model of computation, cf.

T. Kotek, J.A. Makowsky and E.V. Ravve,

A Computational Framework for the Study of Partition Functions and Graph Polynomials

Proceedings of the 12th Asian Logic Conference,

Wellington, New Zealand, 15 - 20 December 2011

Edited by: Rod Downey, Jörg Brendle, Robert Goldblatt and Byunghan Kim.

DOI: 10.1142/9789814449274_0012

Back to overview

Roots of Graph Polynomials

P-roots

It is an established topic to study the locations of the roots of graph polynomials.

For a fixed graph polynomial P(G,X) typical statements about roots are:

- (i) For every G the roots of P(G,X) are real.
- (ii) For every G all real roots of P(G,X) are positive (negative) or the only real root is 0.
- (iii) For every G the roots of P(G,X) are contained in a disk of radius $\rho(p(G))$ where p(G) is some numeric graph parameter (degree, girth, clique number, etc).
- (iv) For every G the roots of P(G,X) are contained in a disk of constant radius.
- (v) The roots of P(G,X) are dense in the complex plane.
- (vi) The roots of P(G,X) are dense in some absolute region.

Studying *P*-roots

We now overview polynomials P for which P-roots have been studied.

- Spectra of graphs, chromatic polynomial, matching polynomial, independence polynomial.
 - Studying the location of their roots is motivated by applications in chemistry, statistical mechanics.
- Edge cover polynomial and domination polynomial. Studying the location of their roots is motivated by analogy only.
- All these polynomials are SOL-definable.
- All are univariate.

Spectral graph theory

Let G(V, E) be a simple undirected graph with |V| = n, and Let A_G and L_G be the (symmetric) adjacency resp. Laplacian matrix of G.

The characteristic polynomial of G is defined as

$$P_A(G,\lambda) = \det(\lambda \cdot 1 - A_G)$$

and the Laplacian polynomial of G is defined s

$$P_L(G,\lambda) = \det(\lambda \cdot 1 - L_G)$$

Theorem 6

The roots of $P_A(G,\lambda)$ and $P_L(G,\lambda)$ are all real.

There is a rich literature.

A.E. Brouwer and W. H. Haemers, Spectra of Graphs, Springer 2010.

Back to overview

The (vertex) chromatic polynomial

Let G = (V(G), E(G)) be a graph, and $\lambda \in \mathbb{N}$.

A λ -vertex-coloring is a map

$$c:V(G)\to [\lambda]$$

such that $(u,v) \in E(G)$ implies that $c(u) \neq c(v)$.

We define $\chi(G,\lambda)$ to be the number of λ -vertex-colorings

Theorem 7 (G. Birkhoff, 1912) $\chi(G,\lambda)$ is a polynomial in $\mathbb{Z}[\lambda]$.

Proof:

- (i) $\chi(E_n) = \lambda^n$ where E_n consists of n isolated vertices.
- (ii) For any edge e = E(G) we have $\chi(G e, \lambda) = \chi(G, \lambda) + \chi(G/e, \lambda)$.

The Four Color Conjecture

Birkhoff wanted to prove the **Four Color Conjecture** using techniques from real or complex analysis.

Conjecture: (Birkhoff and Lewis, 1946)

If G is planar then $\chi(G,\lambda) \neq 0$ for $\lambda \in [4,+\infty) \subseteq \mathbb{R}$.

Theorem 8 (Birkhoff and Lewis, 1946)

For planar graphs G we have $\chi(G,\lambda)\neq 0$ for $\lambda\in [5,+\infty)$.

Still open: Are there planar graphs G such that

 $\chi(G,\lambda)=0$ for some $\lambda\in(4,5)$?

More on chromatic roots, I

For real roots of χ we know:

Theorem 9 (Jackson, 1993, Thomassen, 1997)

For simple graphs G we have $\chi(G,\lambda)\neq 0$ for real $\lambda\in (-\infty,0)$, $\lambda\in (0,1)$ and $\lambda\in (1,\frac{32}{27})$. The only real roots $\leq \frac{32}{27}$ are 0 and 1.

The real roots of all chromatic polynomials are dense in $\left[\frac{32}{27},\infty\right)$

More on chromatic roots, II

For complex roots of χ we know:

Theorem 10 (Sokal, 2004)

The complex roots are dense in \mathbb{C} .

The complex roots are bounded by $7.963907 \cdot \Delta(G) \leq 8 \cdot \Delta(G)$ where $\Delta(G)$ is the maximal degree of G.

We shall see that this is **not** a semantic property of the chromatic polynomial.

However, we have an interpretation in physics:

The chromatic polynomial corresponds to the zero-temperature limit of the antiferromagnetic Potts model. In particular, theorems guaranteeing that a certain complex open domain is free of zeros are often known as Lee-Yang theorems.

The above theorem says that no such domain exists.

More on chromatic roots, III

Theorem 11 (C. Thomassen, 2000)

If the chromatic polynomial of a graph has a real noninteger root less than or equal to

$$t_0 = \frac{2}{3} + \frac{1}{3}\sqrt[3]{26 + 6\sqrt{33}} + \frac{1}{3}\sqrt[3]{26 - 6\sqrt{33}} = 1.29559...$$

Then the graph has no Hamiltonian path.

This result is best possible in the sense that it becomes false if t_0 is replaced by any larger number.

This is not a semantic property of the chromatic polynomial.

A semantic version would be:

The chromatic polynomial determines the existence of Hamiltonian paths..

Back to overview

The three matching polynomials

Let $m_i(G)$ be the number sets of independent edges of size i. We define

$$dm(G,x) = \sum_{r} (-1)^{r} m_{r}(G) x^{n-2r}$$
(6)

$$gm(G,x) = \sum_{r} m_r(G)x^r \tag{7}$$

$$dm(G,x) = \sum_{r} (-1)^{r} m_{r}(G) x^{n-2r}$$

$$gm(G,x) = \sum_{r} m_{r}(G) x^{r}$$

$$M(G,x,y) = \sum_{r} m_{r}(G) x^{r} y^{n-2r}$$
(8)

We have $dm(G; x) = x^n gm(G; (-x)^{-2}) = M(G, -1, x)$ where n = |V|.

All three matching polynomials are d.p-equivalent.

Theorem 12 (Heilmann and Lieb 1972)

The roots of dm(G,x) are real and symmetrically placed around zero, i.e., dm(G, x) = 0 iff dm(G, -x) = 0

The roots of qm(G,x) are real and negative

Back to overview

Independence polynomial

Let $in_i(G)$ be the number of independent sets of G of size i, and the **independence polynomial**

$$I(G,X) = \sum_{i} i n_{i}(G) X^{i}$$

Clearly there are no positive real independence roots.

For a survey see: V.E. Levit and E. Mandrescu,

The independence polynomial of a graph - a survey,

Proceedings of the 1st International Conference on Algebraic Informatics,

Thessaloniki, 2005, pp. 233-254.

J. Brown, C. Hickman and R. Nowakowski showed in Journal of Algebraic Combinatorics, 2004:

Theorem 13 (J. Brown, C. Hickman and R. Nowakowski, 2004) The real roots are dense in $(-\infty, 0]$ and the complex roots are dense in \mathbb{C} .

Back to overview

Edge cover polynomial

Let $e_i(G)$ be the number of edge coverings of G of size i, and the **edge cover** polynomial

$$E(G,X) = \sum_{i} e_{i}(G)X^{i}$$

Theorem 14 (P. Csikvári and M.R.Oboudi, 2011) All roots of E(G,X) are in the ball

$${z \in \mathbb{C} : |z| \le \frac{(2+\sqrt{3})^2}{1+\sqrt{3}} = \frac{(1+\sqrt{3})^3}{4}}.$$

Back to overview

Domination polynomial

Inspired by the rich literature on dominating sets, **S. Alikhani** introduced in his Ph.D. thesis the **domination polynomial**;

Let $d_i(G)$ be the number of dominating sets of G of size i, and the **domination** polynomial

$$D(G,X) = \sum_{i} d_{i}(G)X^{i}$$

It is easy to see that 0 is a domination root, and that there are no real positive domination roots.

J. Brown and J. Tufts (Graphs and Combinatorics, , 2013) showed:

Theorem 15 (J. Brown and J. Tufts)

The domination roots are dense in \mathbb{C} .

Back to overview

D.p.-Equivalence and the Location of the Roots of SOL-Definable Graph Polynomials

From now on all graph polynomials are supposed to be SOL-definable.

Roots vs distinctive power, I

Let s(G) be a similarity function.

Theorem 16 (MRB)

For every univariate graph polynomial $P(G;X) = \sum_{i=0}^{s(G)} h_i(G)X^i$ where s(G) and $h_i(G), i = 0, \dots s(G)$ are graph parameters with values in \mathbb{N} , there exists a univariate graph polynomials $Q_1(G;X)$, prefactor equivalent to P(G;X) such that for every G all real roots of $Q_1(G;X)$ are positive (negative) or the only real root is 0.

Show proof, Skip remaining theorems

Roots vs distinctive power, II

Let s(G) be a similarity function.

Theorem 17 (MRB)

For every univariate graph polynomial

$$P(G;X) = \sum_{i=0}^{i=s(G)} h_i(G)X^i \in \mathbb{Z}[X], \text{ resp. } \mathbb{R}[X]$$

there is a d.p.-equivalent graph polynomial

$$Q_2(G;X) = \sum_{i=0}^{i=s(G)} H_i(G)X^i \in \mathbb{Z}[X], \text{ resp. } \mathbb{R}[X]$$

such that all the roots of Q(G;X) are real.

Show proof, Skip remaining theorems

Roots vs distinctive power, III

Let P(G; X) as before.

Theorem 18 (MRB)

For every univariate graph polynomial P(G;X)

there exist univariate graph polynomials $Q_3(G; X)$

substitution equivalent to P(G; X) such that

for every G the roots of $Q_3(G;X)$ are contained in a disk of constant radius.

If we want to have all roots real and bounded in \mathbb{R} ,

we have to require d.p.-equivalence.

Show proof Skip remaining theorems

Roots vs distinctive power, IV

```
Let P(G; X) as before.
Theorem 19 (MRB)
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For every univariate graph polynomial P(G; X) there exists a univariate graph polynomial $Q_4(G; X)$ prefactor equivalent to P(G; X) such that $Q_4(G; X)$ has only countably many roots, and its roots are dense in the complex plane. If we want to have all roots real and dense in \mathbb{R} , we have to require d.p.-equivalence.

Show proof

The proofs use various tricks!

Skip proofs Back to overview

Proofs: Theorem 16

Let $P(G,X) = \sum_i c_i(G)X^i = \sum_{A \subset V(G)^r} X^{|A|}$ be SOL-definable. We want to show:

For every G all real roots of P(G,X) are negative.

This is true, because all coefficients of P(G,X) are non-negative integers, due to SOL-definability.

If we want to find $Q_1(G; X)$ d.p.-equivalent to P(G; X) such that

for every G all real roots of $Q_1(G,X)$ are positive,

we put
$$Q_1(G,X) = P(G,-X) = \sum_i c_i(G)(-X)^i = \sum_i (-1)^i c_i(G)(X)^i$$
.

If we want to find $Q'_1(G;X)$ d.p.-equivalent to P(G;X) such that

for every G the only real root of $Q_1(G,X)$ is 0,

we put
$$Q'_1(G, X) = P(G, X^2) = \sum_i c_i(G)(X)^{2i}$$
.

Q.E.D.

Go to next theorem, Skip remaining proofs

Proofs: Theorem 17

Let P(G,X) as before be SOL-definable.

We want to find $Q_3(G;X)$ d.p.-equivalent to P(G;X) such that all roots of $Q_2(G;X)$ are real.

We define $Q_2(G; X) = \prod_{i=0}^{s(G)} (X - h_i(G))$.

Q.E.D.

Go to next theorem, Skip remaining proofs

49

Proofs: Theorem 18

Let P(G,X) be SOL-definable.

We want to show:

For every G the roots of $Q_3(G,X)$ are contained in a disk of constant radius.

To relocate the roots of P(G,X) we use Rouché's Theorem in the following form:

Lemma 20

Let $P(X) = \sum_{i=0}^{d} h_i X^i$ and $P'(X) = A \cdot X^{2d}$ with $A \ge \max_i \{h_i : 0 \le i \le d-1\}$. Let $Q_3(X) = P(X) + P'(X)$.

Then all complex roots ξ of $Q_3(X)$ satisfy $|\xi| \leq 2$.

Clearly, P'(G,X) is SOL-definable and d.p. equivalent to P(G,X). Q.E.D.

Reference: P. Henrici, Applied and Computational Complex Analysis, volume 1, Wiley Classics Library, John Wiley, 1988.

Section 4.10, Theorem 4.10c

Go to next theorem, Skip remaining proofs

Proofs: Theorem 19

Lemma 21

There exist univariate similarity polynomials $D^i_{\mathbb{C}}(G;X), i=1,2,3,4$ of degree 12 such that all its roots of $D^i_{\mathbb{C}}(G;X)$ are dense in the *i*th quadrant of \mathbb{C} .

We use this lemma and put

$$Q_4(G; X) = \left(\prod_{i=1}^{i=4} D^i(G; X)\right) \cdot P(G; X).$$

To get the real roots to be dense we proceed similarily.

Q.E.D.

Roots of graph polynomials

Conclusions

Are the locations of P-roots semantically meaningfull?

Our results seems to suggest:

- The location of *P*-roots depends strongly on the syntactic presentation of *P*.
- We still don't understand the particular rôle syntactic presentation of graph polynomials have to play.
- d.p. equivalence garantees that the information conveyed by coefficients or roots is inherent in every presentation.

 The choice of presentation only serves in making it more or less visible.
- Although the location of chromatic roots is easily interpretable, the same is not true for edge cover or domination roots.
- The study of *P*-roots needs better justifications besides mere mathematical curiosity.

The rôle of recurrence relations

The chromatic polynomial, Tutte polynomial and the matching polynomial satisfy **recurrence relations** of the type

$$P(G,X) = \alpha \cdot P(G_{-e},X) + \beta \cdot P(G_{/e}X) + \gamma \cdot P(G_{\dagger e},X)$$

where G_{-e} is deletion of the edge e, $G_{/e}$ is contraction of the edge e, and $G_{\dagger e}$ is extraction of the edge e, and $\alpha, \beta, \gamma \in \mathbb{Z}[X]$ are suitable polynomials.

It is conceivable, and the proofs use these relations, that the location of the corresponding P-roots are intrinsically related to these recurrence relations.

Note: It is not clear how recurrence relations **behave** under d.p. equivalence.

Note: Ilia Averbouch, PhD Thesis, Haifa, February 2011

"Completeness and Universality Properties of Graph Invariants and Graph Polynomials",

http://www.cs.technion.ac.il/janos/RESEARCH/averbouch-PhD.pdf

Thank you for your attention!

Back to overview