On the competitive theory and practice of online list accessing algorithms

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Abstract

This paper concerns the online list accessing problem. In the first part of the paper we present two new families of list accessing algorithms. The first family is of optimal, 2-competitive, deterministic online algorithms. This family, called the MRI (MOVE-TO-RECENT-ITEM) family, includes as members the well known MOVE-TO-FRONT (MTF) algorithm, and the recent, more “conservative” algorithm TIMESTAMP due to Albers. So far MOVE-TO-FRONT and TIMESTAMP were the only algorithms known to be optimal in terms of their competitive ratio. This new family contains a sequence of algorithms \( \{A(i)\}_{i \geq 1} \) where \( A(1) \) is equivalent to TIMESTAMP and the limit element \( A(\infty) \) is MTF. Further, in this class, for each \( i \), the algorithm \( A(i) \) is more conservative than algorithm \( A(i + 1) \) in the sense that it is more reluctant to move an accessed item to the front, thus giving a gradual transition from the conservative TIMESTAMP to the “reckless” MTF. The second new family, called the PRI (PASS-RECENT-ITEM) family is also infinite and contains TIMESTAMP; We show that most algorithms in this family attain a competitive ratio of 3.

In the second, experimental part of the paper, we report the results of an extensive empirical study of the performances of a large set of online list accessing algorithms (including members of our MRI and PRI families). The algorithms’ access cost performances were tested with respect to a number of different request sequences. These include sequences of independent requests generated by probability distributions and sequences generated by Markov sources to examine the influence of locality. It turns out that the degree of locality has a considerable influence on the algorithms’ absolute and relative costs, as well as on their rankings. In another experiment, we tested the algorithms’ performances as data compressors in two variants of the compression scheme of Bentley et al. In both experiments, members of the MRI and PRI families were found to be among the best performing algorithms.

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1 Introduction

In the list accessing problem an online algorithm maintains a set of items as an unsorted linear list. A sequence of requests for items on the list is given and the algorithm must serve these requests in the order of their arrival. Upon a request for an item \( x \), the algorithm must access \( x \) by searching for \( x \) starting from the front of the list. In a standard model of this problem the cost associated with accessing the \( i \)th item from the front is \( i \). The algorithm may reorganise the list at any time. The incentive for such reorganization is to decrease the cost of future accesses. Reorganization is done via a sequence of transpositions of consecutive items. After an item \( x \) is accessed, \( x \) may be moved free of charge to any position closer to the front. Thus the transpositions that bring \( x \) forward after an access are called free exchanges. Any other transposition costs 1 and is called paid.

The above variant of the list accessing problem is called the static model. The dynamic model deals with a dynamic list where new items may be inserted and old items may be deleted (or accessed). Unless otherwise specified we usually assume the static model.

The importance of the list accessing problem arises from the fact that online list accessing algorithms are often used by practitioners. Although organizations of dictionaries as linear lists are relatively inefficient, there are various situations in which a linear list is the implementation of choice. For instance, when the dictionary is small (say for organizing the list of identifiers maintained by a compiler, or for organizing collisions in a hash table), or when there is no space to implement efficient but space consuming data structures, etc. [6, 11]. In addition, any list accessing algorithm can be used as the “heart” of a data compression algorithm [7, 2]. Due to its great relevancy the list accessing problem has been studied since 1965 (see e.g. [15, 19, 6, 21, 17, 3]). Nevertheless, despite these extensive studies, this simple-to-state problem is not yet well understood. In particular, the basic question of which are the best list accessing algorithms and for which inputs, remains unsolved except for two extreme cases, where inputs are independent observations of a probability distribution, or when inputs are generated by an adversary aiming to maximize the multiplicative “regret” of the algorithm (i.e. its competitive ratio, see below). Each of these models implies a different notion of optimality, and the work done so far in this area identified many interesting optimality and approximate-optimality results. However, with respect to hardest “model” of real-life inputs, the problem remains illusive for the most part.

Competitive list accessing algorithms. Let \( \text{ALG} \) be any list accessing algorithm. For any sequence of requests \( \sigma \) we denote by \( \text{ALG}(\sigma) \) the total cost incurred by \( \text{ALG} \) to service \( \sigma \). Following Sleator and Tarjan [21] we measure the performance of an online list accessing algorithm \( \text{ALG} \) by its competitive ratio, defined as follows: we say that \( \text{ALG} \) attains a competitive ratio \( c \) (or that \( \text{ALG} \) is \( c \)-competitive) if there exists a constant \( \alpha \) such that for all request sequences \( \sigma \), \( \text{ALG}(\sigma) \leq c \cdot \text{OPT}(\sigma) + \alpha \) where \( \text{OPT} \) is an optimal offline list accessing algorithm. (The constant \( \alpha \) is usually called the “additive constant”.) If \( \text{ALG} \) is randomized, it is \( c \) competitive against an oblivious adversary if for every request sequence \( \sigma \), \( E[\text{ALG}(\sigma)] \leq c \cdot \text{OPT}(\sigma) + \alpha \) where \( \alpha \) is a constant independent of \( \sigma \), and \( E[\cdot] \) is the mathematical expectation taken with respect to the random choices made by \( \text{ALG} \). The use of the competitive ratio for the analysis of online algorithms is termed competitive analysis.¹

On known competitive optimal list accessing algorithms and their applications. In their seminal paper, Sleator and Tarjan [21] showed that the well-known algorithm MOVE-TO-FRONT (MTF), a deterministic algorithm that moves each requested item to the front, is 2-competitive. Raghavan and Karp (reported in [12]) proved a lower bound of \( 2 - 2/(\ell + 1) \) on the competitive ratio of any deterministic algorithm maintaining a list of size \( \ell \). Irani [12] gave a matching upper bound for MTF showing that MTF is a strictly optimal online algorithm judged from the perspective of competitive

¹The term “competitive analysis” was coined by Karlin et al. [14].
analysis. Recently, Albers [1] discovered another deterministic algorithm called \textsc{timestamp} and proved that it is 2-competitive. So far \textsc{mtf} and \textsc{timestamp} have been the only deterministic algorithms known to attain an optimal competitive ratio of 2.\footnote{Any deterministic list accessing algorithm is termed here \textit{optimal} if it attains a competitive ratio of 2. An algorithm which attains the upper bound of $2 - 2/(\ell + 1)$ is termed \textit{strictly optimal}.}

The importance and practical usefulness of algorithm \textsc{mtf} has been well known for quite some time (see e.g. Bentley and McGeoch [6]). This algorithm provides a very simple and efficient method of maintaining a linked list with a guaranteed performance. Further, \textsc{mtf} can be used to devise a very simple and successful (text) compression algorithm (see e.g. [7, 9, 10]).

Soon after its discovery, algorithm \textsc{timestamp} was also shown to play an important role. Continuing Albers’ work, Albers, von Stengel and Werchner [3] combined \textsc{timestamp} and algorithm \textsc{bit} [17, 13] in a 1/5-4/5 probability mixture and showed that the resulting randomized algorithm (called \textsc{comb}) is 8/5-competitive against an oblivious adversary. So far this is the best known randomized upper bound that leaves a small gap to the best known lower bound of 3/2 [22]. Another work due to Albers and Mitzenmacher [2] demonstrated the usefulness of \textsc{timestamp} by considering it as an engine for the data compression scheme of Bentley \textit{et al.} [7, 2]. With respect to the Calgary Corpus, a collection of standard benchmark files for (text) compression [5], they found that the \textsc{timestamp}-based compression algorithm is in most cases superior to the \textsc{mtf}-based one. They argued that this phenomenon is related to the fact that \textsc{timestamp} is more “conservative” than \textsc{mtf} and therefore it is better suited to the degree of \textit{locality of reference} exhibited in (the corpus) text files.

These results concerning \textsc{mtf} and \textsc{timestamp} emphasize compelling arguments supporting the quest for other deterministic (list accessing) algorithms, and in particular, optimal ones.\footnote{Another variant of \textsc{mtf} that moves an item to the front every other access can be also shown to be 2-competitive.} First, different (optimal) deterministic algorithms have different behaviors on different input sequences and by identifying the characteristic behaviors with respect to various inputs one can better match an algorithm to the task in question. For instance, it could be rewarding to be able to match (or adapt online) the choice of a list accessing algorithm to varying degrees of locality of reference exhibited in the input. Also, a set of (optimal) deterministic algorithms can be used to obtain randomized algorithms by considering probability distributions over the set. The discovery of algorithm \textsc{comb} is an important example for such possibilities. (Note that algorithm \textsc{bit}, the randomized component of \textsc{comb}, is in fact a uniform probability mixture over a set of $2^\ell$ deterministic algorithms each of which is 2-competitive.)

In the first part of this paper we introduce two new families of deterministic online list accessing algorithms. We analyze one of the families and provide some initial results regarding algorithms of the second family.

The list accessing problem has been studied for Despite the (over) thirty years of list accessing research, with plenty of interesting theoretical results, this topic suffers from a lack of experimental feedback that could lead to better and more realistic theory. In the second part of this paper we report the results of extensive empirical study testing the access cost performance and compression performance of more than 40 list accessing algorithms. These include many well known as well as our new algorithms.
1.1 Contents and paper organization

The paper is organized as follows. In Section 2 we introduce the new MRI and PRI families and state our results. In Section 3 we develop some techniques that will be used later in the analyses of the MRI and PRI families. In particular, we present some features of the well-known "list factoring" technique that in this paper will be used only for lower bounding optimal offline costs. In Section 4 we prove the optimality of the algorithms in the MRI family and prove the equivalence between MRI(1) and TIMESTAMP. We also prove a lower bound of $\Omega(\sqrt{f})$ on the competitive ratio of algorithm MRI(0). In Section 5 we extend our results to the dynamic list model.

The second part of the paper starts in Section 6 and is concerned with the results of an extensive experimental study of many list accessing algorithms. In Section 6.1 we describe all the algorithms tested. These include representatives of 18 different families and more than 40 algorithms in all. Whenever known we specify bounds on the competitive ratios of the algorithms described. We have performed two experiments. The first attempts to rank the various algorithms in terms of their access cost performance, and the second, in terms of their performance as data compressors. General descriptions of these two experiments are given in Sections 6.2 and 6.3. Sections 7 and 8 treat each of these experiments in detail. In particular, they describe the data sets, the experiments, the conclusions and other relevant and related experiments. Finally, in Section 9 we draw our conclusions.

2 New list accessing algorithms

In this section we present new deterministic list accessing algorithms. In particular, we introduce two classes of algorithms called the MRI and the sc PRI families.

2.1 The MRI Family

Let $m$ be a non-negative integer. Consider the following deterministic list accessing algorithm called MOVE-TO-RECENT-ITEM($m$) (or MRI($m$) for short).

Algorithm MRI($m$): Upon a request for item $x$, move $x$ forward just after the last item $z$ on the list that is in front of $x$ and that was requested at least $m+1$ times since the last request for $x$. If there is no such item $z$ or if this is the first request for $x$, move $x$ to the front.

We call the set of algorithms $\{\text{MRI}(m)\}_{m \geq 0}$ "the MRI Family". In this paper we prove that the MRI Family includes all deterministic list accessing algorithms that are so far known to be optimal (i.e. MTF and TIMESTAMP). First, notice that MTF is the limit element of the MRI Family as $m$ approaches infinity. In fact, for each particular (finite) request sequence $\sigma$ each of the algorithms MRI($m$) with $m \geq |\sigma|$ is equivalent to MTF with respect to $\sigma$ (i.e. it acts identically to MTF). As noted above MTF is optimal. Let us now describe algorithm TIMESTAMP due to Albers [1]5.

Algorithm TIMESTAMP: Upon a request for an item $x$, insert $x$ in front of the first (from the front of the list) item $y$ that precedes $x$ on the list and was requested at most once since the last request for $x$. Do nothing if there is no such item $y$, or if $x$ has been requested for the first time.

5The precise name of TIMESTAMP in [1] is TIMESTAMP(0).
The algorithms in the MRI family and in particular, MRI(1) look similar to algorithm timestamp. Indeed, all these algorithms maintain and use time “stamps” in order to determine their actions. Note the following two differences between MRI(1) and timestamp. The first difference is in the manner they handle first requests for items: upon a first request for an item \( x \), timestamp keeps \( x \) in place whereas MRI(1) moves \( x \) to the front. The second difference is that MRI(1) moves the requested item \( x \) forward to a position just after the last element in front of \( x \) that was requested at least twice since the last request for \( x \) whereas timestamp moves \( x \) forward just before the first element in front of \( x \) that was requested at most once since the last request for \( x \). The first difference is of minor significance. The second difference, although subtle, appears to be (at least at the outset) of major significance. Nevertheless, later we shall prove that MRI(1) and timestamp are equivalent (modulo the above first difference).

**Proposition 1** Algorithms MRI(1) and timestamp are equivalent.

(The precise definition of this equivalence will be given later, in Section 4.1.)

For each \( i \geq 0 \), algorithm MRI(\( i \)) appears more “reluctant” than algorithm MRI(\( i + 1 \)) to move an accessed item forward. This property makes the MRI family attractive as it provides a gradual transition from the “conservative” timestamp to the more “hasty” MTF. An example that demonstrates this feature will be presented. In particular this property of the MRI family may be used in applications to dynamically adapt to varying degrees of locality of reference, by “shifting gears” between algorithms in the MRI family.

**Theorem 1** For any list of size \( \ell \) and for each integer \( m \geq 1 \), MRI(\( m \)) is \( (2 - 1/\ell) \)-competitive in the static model.\(^6\)

This result significantly expands our knowledge of competitive-optimal deterministic list accessing algorithms. The proof of Theorem 1 (Section 4) uses a standard potential function argument in conjunction with standard list factoring (to bound below the optimal offline cost). These two techniques have been usually used separately. Note that standard list factoring by itself cannot be employed for proving upper bounds for the MRI family (except when \( m = 1 \)). The reason is that for \( m > 1 \) algorithm MRI(\( m \)) does not satisfy the “Pairwise Property” [6]. On the other hand, we could not obtain a pure potential function proof. It is interesting to note that both MTF and timestamp do satisfy the Pairwise Property and thus allow for a standard and simple list factoring analysis (as well as a potential function analysis).

The “odd” element of the MRI family is the algorithm MRI(0) which is no better than \( \Omega(\sqrt{\ell}) \)-competitive. This is established in Section 4.2. It is interesting to note that in the experimental study, presented later in this paper, members of the MRI family and in particular MRI(0) were found to be among the best list accessing algorithms in terms of their access cost performance (as well as data compressors).

Theorem 1 also holds within the dynamic list accessing model (in which case \( \ell \) is the total number of elements that were inserted to the list). This is established in Section 5.

### 2.2 The PRI Family

Analogous to the MRI Family and generalizing the algorithm timestamp of Albers in a straightforward manner, we now define the following family of algorithms. Let \( m \) be a non-negative

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\(^6\)As pointed out by an anonymous referee it is possible to prove that MRI(\( m \)), \( m \geq 1 \), attain the optimal upper bound of \( 2 - 2/(\ell + 1) \) using a different proof technique than ours.
integer. Consider the following deterministic list accessing algorithm called \textsc{pass-recent-item}(m) (or \textsc{pri}(m) for short).

\textbf{Algorithm} \textsc{pri}(m): Upon a request for item \(x\), move \(x\) forward just in front of the first item \(z\) on the list that was requested at most \(m\) times since the last request for \(x\).  
Do nothing if there is no such item \(z\). If this is the first request for \(x\), move \(x\) to the front.

We call this infinite set of algorithms \(\{\text{pri}(m)\}_{m \geq 0}\), “the PRI Family”. It is readily seen that algorithm \textsc{pri}(1) is identical to algorithm \textsc{timestamp} (modulo handling of first requests). Here again, the limit algorithm of this family (as \(m\) approaches infinity) is \(\text{mtf}\). We state without a proof the following result.\footnote{The proof of Proposition 2 has a similar structure to the proof of Theorem 1.}

\textbf{Proposition 2} For all \(m \geq 1\) \textsc{pri}(m) is 3-competitive.

The exact competitive ratio of the algorithm in the PRI Family (other than \textsc{pri}(1)) is an open question.

It is not hard to see that for all \(m \neq 1\) \((m \geq 0)\) \textsc{pri}(m) acts differently than \textsc{MRI}(m); Consider the following example.

\textbf{Example 1}: Consider a list of 5 elements initially ordered \((1, 2, 3, 4, 5)\) where the element 1 is at the front. Consider the following request sequence

\[
\sigma = 5, 4, 3, 2, 1, 1, 3, 1, 3, 2, 4, 5, 1, 3, 1, 3, 2, 5, 2, 5, 1, 1, 4, 5, 5, 4, 2.
\]

Consider algorithm \textsc{MRI}(2). After processing \(\sigma\) the list maintained by \textsc{MRI}(2) is \((4, 5, 2, 1, 3)\) and the cost it incurs is 87. For comparison consider algorithms \textsc{pri}(1) = \textsc{timestamp}, \textsc{pri}(2), and \textsc{mtf}. The costs incurred by these algorithms for processing \(\sigma\) are, respectively, 95, 93 and 93 and they end up with the following lists, respectively: \((5, 4, 1, 2, 3)\), \((2, 4, 5, 1, 3)\) and \((2, 4, 5, 1, 3)\). Thus, in some sense algorithms \textsc{MRI}(2), \textsc{PRI}(1) and \textsc{PRI}(2) all have different “predictions” for what is likely to be the next request.

\textbf{Example 2}: We now consider three request sequences, each of which distinguishes between the algorithms \textsc{MRI}(m), \(m = 1, 2, \ldots, 8\) in a different way. The following are the three sequences.

\[
\begin{align*}
\sigma_1 &= 54321544232314211112314324252124214235423541421231314443251444214 \\
&\quad 23123231433143232352423312332425234235133; \\
\sigma_2 &= 5432121131252135113352423311135455425544421354554332324212431333 \\
&\quad 11142423312311355242421311324525435124525421243323142124332421 \\
&\quad 31252143; \\
\sigma_3 &= 5432131251444325252524543121442335554511135442443212551333311254 \\
&\quad 45454235435511323211312525233112112311121423554255542451133.
\end{align*}
\]

The respective costs of the algorithms for each of these sequences are summarized in Table 1. As can be seen in Table 1, with respect to \(\sigma_1\) the minimum cost of 314 is obtained by \textsc{MRI}(1) and the cost monotonically increases with \(m\), so that the maximum cost of 356 is obtained by both
\[
\begin{array}{cccccccc}
\text{MRI}(1) & \text{MRI}(2) & \text{MRI}(3) & \text{MRI}(4) & \text{MRI}(5) & \text{MRI}(6) & \text{MRI}(7) & \text{MRI}(8) \\
\sigma_1 & 314 * & 323 & 330 & 340 & 349 & 352 & 356 & 356 \\
\sigma_2 & 449 & 435 & 414 & 407 * & 411 & 415 & 415 & 418 \\
\sigma_3 & 418 & 399 & 391 & 386 & 382 & 375 & 372 & 368 * \\
\end{array}
\]

Table 1: The costs of MRI(m), m = 1, 2, ..., 8 with respect to \( \sigma_i \), i = 1, 2, 3. The minimum cost in each row is marked by *.

\( \text{MRI}(7) \) and \( \text{MRI}(8) \). With respect to \( \sigma_2 \), the minimum cost is obtained by \( \text{MRI}(4) \) and the sequence of costs incurred by \( \text{MRI}(m) \), m = 1, 2, 3, 4 is monotone decreasing; on the other hand, the sequence of costs incurred by \( \text{MRI}(m) \), m = 4, ..., 8 is monotone increasing. Lastly, with respect to \( \sigma_3 \) the minimum cost is obtained by \( \text{MRI}(8) \) and the sequence of costs for \( \text{MRI}(m) \) is a monotone decreasing with m.

3 Preliminaries and list factoring

We begin by introducing some notation that will be used throughout. Let \( \{x_1, x_2, \ldots, x_L\} \) be a set of items. These items are the (fixed) set of items on the list, \( L \). Let \( \sigma = r_1, r_2, \ldots, r_n \) be any request sequence with \( r_i \in L \). For each pair of items \( x, \ y \ (x \neq y) \) denote by \( \sigma_{xy} \) the “projection” of \( \sigma \) over \( x \) and \( y \), defined to be \( \sigma \) after deletion of all the requests for items other than \( x \) and \( y \). Similarly we define \( L_{xy} \) to be the projection of the list \( L \) over \( x \) and \( y \) (i.e. \( L_{xy} \) is the two element list holding \( x \) and \( y \)).

The list factoring technique was first discovered by Bentley and McGeoch [6] and was extended and used in several papers [12, 22, 3]. This technique enables a reduction of the cost analysis of list accessing algorithms to lists of size two. In this paper we use this technique only to bound from below the optimal offline cost. We now present parts of this technique that are essential to our analysis or to the discussion that follows.

Call the variant where we charge \( i - 1 \) for accessing the \( i \)th item on the list the partial-cost model. The usual model where we charge \( i \) for accessing the \( i \)th item will be called the full-cost model. For any list accessing algorithm \( \text{ALG} \) and request sequence \( \sigma \) denote by \( \text{ALG}^*(\sigma) \) the cost incurred by \( \text{ALG} \) for serving \( \sigma \) within the partial-cost model.

Suppose \( \text{ALG} \) is a deterministic list accessing algorithm that does not use paid exchanges. Let \( \sigma = r_1, r_2, \ldots, r_n \) be any request sequence. For each item \( x \in L \), and integer \( 1 \leq j \leq n \), we denote by \( \text{ALG}(x, r_j) \) a cost function measuring the penalty attributed to item \( x \) for being in the way while \( \text{ALG} \) accesses \( r_j \) (the \( j \)th request). That is

\[
\text{ALG}(x, r_j) = \begin{cases} 
1 & \text{if } x \text{ is in front of } r_j, \\
0 & \text{otherwise (including the case } x = r_j). 
\end{cases}
\]

Using the above notation and this cost function we have,

\[
\text{ALG}^*(\sigma) = \sum_{1 \leq j \leq n} \sum_{x \in L} \text{ALG}(x, r_j) \\
= \sum_{x \in L} \sum_{1 \leq j \leq n} \text{ALG}(x, r_j)
\]
\[
= \sum_{x \in L} \sum_{y \in L} \sum_{j: r_j = y} \text{ALG}(x, r_j) \\
= \sum_{x, y \in L} \sum_{j: r_j = y} \text{ALG}(x, r_j) \\
= \sum_{\{x, y\} \subseteq L} \sum_{j: r_j \in \{x, y\}} \left[ \text{ALG}(x, r_j) + \text{ALG}(y, r_j) \right]. \tag{2}
\]

For every \(x\) and \(y\) in \(L\), and request sequence \(\sigma\) we denote the internal summation of the expression in (2) by \(\text{ALG}_{xy}^*(\sigma)\). That is,

\[
\text{ALG}_{xy}^*(\sigma) = \sum_{j: r_j \in \{x, y\}} \left[ \text{ALG}(x, r_j) + \text{ALG}(y, r_j) \right].
\]

We can now write equation (2) as

\[
\text{ALG}^*(\sigma) = \sum_{\{x, y\} \subseteq L} \text{ALG}_{xy}^*(\sigma). \tag{3}
\]

Define \(\text{ALG}^*(\sigma_{xy})\) to be the cost that \(\text{ALG}\) pays for serving the projected request sequence \(\sigma_{xy}\) while operating on the projected list \(L_{xy}\). We say that the algorithm \(\text{ALG}\) satisfies the Pairwise Property if for every pair \(\{x, y\} \subseteq L\), \(\text{ALG}^*(\sigma_{xy}) = \text{ALG}_{xy}^*(\sigma)\).

Which online algorithms satisfy the Pairwise Property? The following is a useful characterization due to Bentley and McGeoch [6]: An algorithm satisfies the Pairwise Property iff for every request sequence \(\sigma\), when \(\text{ALG}\) serves \(\sigma\), the relative order of every two elements \(x\) and \(y\) in \(L\) is the same as their relative order in \(L_{xy}\) when \(\text{ALG}\) serves \(\sigma_{xy}\).

Equations (2) and (3) do not in general apply to an optimal offline algorithm, \(\text{OPT}^*(\text{OPT}^*)\) as in general, \(\text{OPT}\) cannot avoid paid exchanges.\(^8\) Nevertheless, it is not hard to obtain the following inequality

\[
\sum_{\{x, y\} \subseteq L} \text{OPT}^*(\sigma_{xy}) \leq \text{OPT}^*(\sigma) \tag{4}
\]

Moreover, it is possible to extend this inequality to the full cost model. This is established in the following lemma.

**Lemma 1** For any request sequence \(\sigma\),

\[
\sum_{\{x, y\} \subseteq L} \text{OPT}(\sigma_{xy}) \leq \text{OPT}(\sigma)
\]

The proof of inequality (4) and Lemma 1 can be found in [8]. (For the reader’s convenience we included them in Appendix A. What makes Lemma 1 so useful is the fact that the optimal offline algorithm, restricted to lists of size two, has a very simple structure\(^9\) (in fact, it is not unique and we refer to one particular optimal offline algorithm), which is summarized in the following lemma.

\(^8\)The following example due to Reingold and Westbrook [17] proves this assertion. Consider a list \(L = \{x_1, x_2, x_3\}\) of size 3 initially ordered \(x_1, x_2, x_3\) (\(x_1\) at the front). The optimal offline cost to serve the request sequence \(x_3, x_2, x_3, x_2\) is 8. An optimal offline algorithm without paid exchanges pays 9 to serve the same sequence.

\(^9\)The best known list accessing optimal offline algorithm for lists of sizes \(\ell\) larger than 2 [17] does not have a concise description, which is probably essential to make it useful for analyses. We note that this algorithm computes the optimal solution in time exponential in \(\ell\).
Lemma 2 Assume \( L \) is a list of two elements \( x \) and \( y \). Then there exists an optimal offline algorithm \( \text{opt} \) for \( L \) that satisfies the following properties: (i) \( \text{opt} \) does not use paid exchanges; and (ii) Whenever there is a run of two or more consecutive requests for \( x \) (or \( y \)), \( \text{opt} \) moves \( x \) (or \( y \)) to the front (if it is not already there) after the first request (of this run) using free exchanges.\(^{10}\)

The proof of Lemma 2 is simple and is left to the reader.

This lemma will be essential to our analyses. Using it in conjunction with Lemma 1, one can easily bound the optimal offline cost to serve a request sequence \( \sigma \) by summing up the costs \( \text{opt}(\sigma_{xy}) \) for every pair \( \{x, y\} \subseteq L \).

Let \( \text{opt} \) be any optimal offline list accessing algorithm and let \( L \) be a list of \( \ell \) items. Denote by \( \text{FOPT} \) (“factored” \( \text{opt} \)) the collection of all \( \binom{\ell}{2} \) 2-element lists \( L_{xy} \) with \( \{x, y\} \subseteq L \) that are each maintained by an optimal offline algorithm satisfying properties (i) and (ii) of Lemma 2. Let \( \sigma \) be any request sequence. Abusing notation, we shall refer to \( \text{FOPT} \) both as the set of all these 2-element lists and also as the optimal offline algorithm that maintains these lists and serves the request sequences \( \sigma_{xy} \) (\( \{x, y\} \subseteq L \)). Define \( \text{FOPT}_i \), to be the cost incurred by \( \text{FOPT} \) to serve the \( i \)th request in \( \sigma \) in the full cost model. Formally, if the \( i \)th request is for an element \( x \) then \( \text{FOPT}_i \) is defined to be one plus the number of 2-element lists \( L_{xy} \in \text{FOPT} \) that contain \( x \) in the second position. By the definition of the extended cost function (10) it is clear that

\[
\sum_{i=1}^{\vert \sigma \vert} \text{FOPT}_i = \sum_{\{x, y\} \subseteq L, x \neq y} \text{OPT}(\sigma_{xy})
\]

Therefore, using Lemma 1 we obtain

Lemma 3

\[
\sum_{i=1}^{\vert \sigma \vert} \text{FOPT}_i \leq \text{OPT}(\sigma)
\]

4 Analysis of the MRI Family

We use the following notation. Suppose \( L \) is the list maintained by some algorithm. For each pair of items \( x \) and \( y \) in \( L \), we say that \( (x, y) \) in \( L \)” when \( x \) is currently in front of \( y \) in \( L \). If \( (x, y) \) in the list maintained by the online algorithm but \( (y, x) \) in the list maintained by the optimal offline algorithm then we say that \( (x, y) \) is an inversion. With respect to \( \text{MRI}(m) \) consider a request for an item \( x \). Define \( p(x) \), the current pivot of \( x \) to be the last element on the list that is in front of \( x \) and was requested at least \( m + 1 \) times since the last request for \( x \). If there is no such element or if this is the first request for \( x \) then \( p(x) \) is undefined. Thus, upon a request for an element \( x \), \( \text{MRI}(m) \) moves \( x \) one position after \( p(x) \), and if \( p(x) \) is undefined, \( x \) is moved to the front.

Fix any request sequence \( \sigma \) and set \( L \) to be the \( \ell \)-item list maintained by \( \text{MRI}(m) \). We compare configurations of \( L \) to configurations of \( \text{FOPT} \). Consider any configuration of \( L \) and a configuration of \( \text{FOPT} \). For each (ordered) pair of items \( (x, y) \subseteq L, x \neq y \), we define the following weight function

\(^{10}\)In fact, it is not hard to see that an optimal offline algorithm (for lists of size two) that satisfies property (i) must satisfy property (ii).
\[ w(x, y) = w(x, y, L, \text{FOPT}) = \begin{cases} 
0, & \text{if } (x, y) \text{ is not an inversion;} \\
1, & \text{if } (x, y) \text{ is an inversion and } y \text{ will pass } x \\
2, & \text{if } (x, y) \text{ is an inversion and } y \text{ will pass } x \text{ in } L \text{ if } y \text{ is requested next;}
\end{cases} \]

It is easy to verify that \( w(x, y) \) is well defined. Moreover \( w(x, y) \) satisfies the following independence property that is essential for the proof of Theorem 1: the weight of two elements \( y \) and \( z \) cannot be increased (from \( 1 \) to \( 2 \)) after a request for \( x \) is made.

**Lemma 4** Let \( m > 0 \) be given. Let \( y \) and \( z \) be two elements such that \( (z, y) \) in \( L \) is an inversion with \( w(z, y) = 1 \). Let \( x \) be any element other than \( y \) and \( z \). Then \( w(z, y) \) remains \( 1 \) after a request for \( x \) is serviced by \( \text{MRI}(m) \).

**Proof:** The proof is by contradiction. Consider a configuration of \( L \) with \( (z, y) \) in \( L \) an inversion with \( w(z, y) = 1 \). Consider the \( i \)th request for an element \( x \), \( x \neq y \), \( x \neq z \), and assume that after \( \text{MRI}(m) \) processes this request for \( x \), the weight \( w(z, y) \) increases from \( 1 \) to \( 2 \). By the definition of the function \( w \) it must be that due to this request for \( x \), \( \text{MRI}(m) \) positions \( x \) in between \( y \) and \( z \) so that \( x \) becomes the pivot of \( y \). This means that the pivot of \( x \) just before the \( i \)th request, \( p(x) \), is an element located in front of \( y \) and after \( z \) (or \( p(x) = z \) itself). Set \( p = p(x) \). Since after the service of the \( i \)th request \( x \) becomes the pivot of \( y \) it must be that after servicing the \( i \)th request there were \( m + 1 \) requests for \( x \) since the last request for \( y \). In between the times of the two last requests for \( x \) there must be \( m + 1 \) requests for \( p \). As \( m \geq 1 \) the second last request for \( x \) occurred after the last request for \( y \) which means that \( p \) was a pivot of \( y \) even before \( \text{MRI}(m) \) serviced the \( i \)th request for \( x \). But this means that \( w(z, y) = 2 \) before the \( i \)th request in contradiction to our assumption. It follows that \( w(z, y) \) cannot increase from \( 1 \) to \( 2 \). Note also that \( w(z, y) \) cannot decrease to \( 0 \) if \( z \) or \( y \) are not requested.

We now define the following potential function.

\[ \Phi = \Phi(L, \text{FOPT}) = \sum_{\{x, y\} \subseteq L, x \neq y} w(x, y). \]

It is clear that \( \Phi \) is bounded below as it is always non-negative. Let \( \sigma = r_1, r_2, \ldots, r_n \) be any request sequence. The *amortized cost* \( a_i \) for \( \text{MRI}(m) \) to serve the \( i \)th request is defined as \( a_i = \text{MRI}(m), \Phi_i \) where \( \text{MRI}(m), \Phi_i \) is the *actual cost* incurred by \( \text{MRI}(m) \) while serving \( r_i \), and \( \Delta \Phi_i = \Phi_i - \Phi_{i-1} \) is the difference of the potential after both \( \text{MRI}(m) \) and \( \text{FOPT} \) served \( r_i \) minus the potential before their moves). Similarly, define \( \text{FOPT}_i \) to be the actual cost incurred by \( \text{FOPT} \) while serving \( r_i \). We shall use the standard potential function technique that is summarized in the following simple lemma [21, 8]

**Lemma 5** Suppose that (i) \( \Phi \) is bounded below; and (ii) there is a positive constant \( c \) such that for each \( i = 1, 2, \ldots, n \), \( \text{MRI}(m), \Phi \leq c \cdot \text{FOPT}_i \). Then \( \text{MRI}(m) \) is \( c \)-competitive.

**Proof of Theorem 1** Imagine that algorithms \( \text{MRI}(m) \) and \( \text{FOPT} \) are working concurrently and processing the request sequence \( \sigma \). Consider the \( i \)th request \( (r_i) \) for some item \( x \). At the penalty of
increased additive constant assume that \( r_i \) is not the first request for \( x \). (We can pad the request sequence \( \sigma \) with a prefix consisting of \( \ell \) requests, one for each item. The additional cost due to this prefix can be attributed to the additive constant and will not alter the competitive ratio.) Assume that just before this request is revealed, \( x \) is located at the \( k \)th position in \( L \) and that \( x \) appears at the second position (i.e. last position) in \( j \) of the 2-item lists in \( \text{Fopt} \). The former assumption means in particular that the actual cost for \( \text{MRI}(m) \), is \( \text{MRI}(m) = k \). Similarly, the latter assumption implies that \( \text{Fopt}_i = j + 1 \).

Define \( J \) to be the set of elements \( z \) such that \( \langle z, x \rangle \) in \( L \) is an inversion (i.e. \( \langle z, x \rangle \) in \( L \) but \( \langle x, z \rangle \) in \( L_{xz} \in \text{Fopt} \)). Define \( C \) to be the set of elements \( z \) such that \( \langle z, x \rangle \) in \( L \) is not an inversion, and define \( S \) to be the set of elements \( z \) such that \( \langle x, z \rangle \) in \( L \) is an inversion. Set \( I = |J| \), \( C = |C| \) and \( S = |S| \).

We are now in a position to bound the amortized cost \( a_i \). First consider the change in potential after \( \text{MRI}(m) \)’s move due to inversions in \( L \) corresponding to elements in \( I \). By the definitions of \( \text{MRI}(m) \) and of the weight function \( w \), if in \( L \) an element \( z \in J \) is passed by \( x \), the weight of the inversion \( \langle z, x \rangle \) in \( L \) was 1 before the move and this inversion is eliminated by this move. An element \( z \) corresponding to an inversion \( \langle z, x \rangle \) that is not passed by \( x \), contributed (together with \( x \)) a weight of 2 before the move and by the definition of \( \text{MRI}(m) \) and \( w \), reduces this weight to 1 after \( \text{MRI}(m) \) moves \( x \). Hence there is a decrease of exactly \( I \) in \( \Phi \) due to elements in \( I \). Due to \( \text{MRI}(m) \)’s move and before \( \text{Fopt} \) moves, the weight of each inversion \( \langle x, z \rangle \) in \( L \) with \( z \in S \) may increase by one giving a total increase of up to \( S \).

Since \( \text{Fopt} \) does not use any paid exchanges its move cannot affect the above change in potential due to inversions corresponding to elements in \( I \). (Of course, \( \text{Fopt} \)’s move can eliminate inversions due to elements in \( S \); this possibility will be considered next.)

We shall make use of the following claim.

**Claim 1** If, in the list \( L \), \( x \) passes an element \( z \in C \) then \( z \) was requested at least once since the last request for \( x \).

To prove this claim suppose that \( z \in C \) was not requested at all since the last request for \( x \). It follows (property (ii) of Lemma 2) that \( z \) cannot be in \( C \) since \( \text{Fopt} \) would have moved \( x \) in front of \( z \) in \( L_{xz} \) before this request for \( x \). Hence, if an element \( z \in C \) is passed by \( x \), then \( z \) was requested at least once since the last request for \( x \), which proves the above claim.

Suppose that a new inversion \( \langle x, z \rangle \) in \( L \) is created (i.e. \( x \) does not pass \( z \) in \( L_{xz} \) but \( x \) does pass \( z \) in \( L \)). By definition of the weight function, the weight of this new inversion is 1 if and only if \( z \) will pass \( x \) if \( z \) is requested next. We now show that this is indeed the case (i.e. that if the subsequent request is for \( z \), then \( z \) will pass \( x \)).

Consider the configuration of \( L \) just after \( \text{MRI}(m) \) serves the \( i \)th request. By our assumption, \( x \) has just moved in front of \( z \). Consider any element \( y \) that is now positioned between \( x \) and \( z \); that is, in the last move \( x \) also passed \( y \) and now in \( L \), \( x \) appears in front of \( y \), which appears in front of \( z \). Suppose that the previous request for \( x \) is \( r_{i'} \). By the definition of \( \text{MRI}(m) \) since \( x \) passed \( y \), it must be that \( y \) was requested at most \( m \) times between the last \( i \)th and second last \( i' \)th requests for \( x \). Assume that the next request \( r_{i+1} \) is for \( z \). Then \( z \) will pass \( x \) if and only if the following two conditions hold: (i) all items \( y \) now appearing between \( x \) and \( z \) were requested at at most \( m \) times between the current (i.e. \( (i + 1) \)st) and last request for \( z \); and (ii) \( x \) was requested at most \( m \) times since the last request for \( z \). Since, by the above claim, \( z \) was requested at least once between the two most recent request for \( x \), and since any such item \( y \) was requested at most \( m \) times between the two most recent requests for \( x \) it must be that these two conditions hold.
Therefore if \(r_{i+1} = z\), the element \(z\) will pass \(x\) and the weight of the new inversion \((x, z) \in L\) (if it is created) is exactly 1.

Other possibilities for new inversions are when for some element \(z \in C\), in \(L_x\), \(x\) passes \(z\) but \(x\) does not pass \(z\) in \(L\), the weight of a new such inversion must be 1 as well, since the last request was for \(x\) so an additional request for \(x\) will move \(x\) to the front of \(L\). It follows that the increase in \(\Phi\) due to new inversions created is at most \(C\).

It is easy to see that the following identities hold.

\[
\begin{align*}
  k - 1 & = C + I \\
  j & = S + C.
\end{align*}
\]

For example, to justify the first identity notice that the elements that are in front of \(x\) in \(L\) (just before the \(i\)th request) are exactly those that are either in \(C\) or in \(I\) and these sets are disjoint. The second identity follows from the definitions of \(j\), \(S\) and \(C\). From these identities it readily follows that \(k = I + j - S + 1\) and that \(C \leq j\). Here again \(j \leq \ell - 1\).

Putting all this together, the amortized cost \(a_i\) for \(\text{MRI}(m)\) to serve the \(i\)th request is bounded above as follows.

\[
a_i \leq k - I + S + C \\
= I + j - S + 1 - I + S + C \\
= j + C + 1 \\
\leq 2j + 1 \\
\leq (2 - 1/\ell) \cdot (j + 1) \leq (2 - 1/\ell) \cdot \text{popt}_{I_i}.
\]

Using lemmas 5 and 3 we conclude that \(\text{MRI}(m)\) is \((2 - 1/\ell)\)-competitive. 

\[\Box\]

4.1 The equivalence of \(\text{MRI}(1)\) and TIMESTAMP

Consider algorithm TIMESTAMP (see Section 2.1). Here we prove that except for the difference in handling first requests for items algorithm TIMESTAMP is equivalent to algorithm MRI(1). Specifically, we shall prove that if we alter the definition of either MRI(1) TIMESTAMP (or both) so that they handle first requests for items in the same manner, then the two algorithms are equivalent in the sense that they process any request sequence in exactly the same manner.

**Lemma 6** Each of the algorithms TIMESTAMP and MRI(1) maintains the following invariant: upon a request for \(x\), all the items that are requested twice or more since the last request for \(x\) are in front of all items that were requested less than twice since the last request for \(x\).

Using Lemma 6 we learn that upon a request for an item \(x\) both \(\text{MRI}(1)\) and TIMESTAMP move \(x\) forward just after all the elements that were requested twice or more since the last request for \(x\) (equivalently, just in front of all the elements that were requested less than twice since the last request for \(x\)). This means that both algorithms maintain identical lists at all times. Hence we have proved Proposition 1.

Interestingly, other algorithms in the MRI Family (i.e. \(m \neq 1\)) do not maintain analogous invariants. For example the algorithm MRI(0) does not maintain the following invariant: “upon a request for \(x\), all the items that are requested once or more since the last request for \(x\) are in front of all items that were not requested since the last request for \(x\)”.

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4.2 The algorithm \(\text{MRI}(0)\)

Algorithm \(\text{MRI}(0)\) is significantly more “conservative” than \(\text{MRI}(1)\) (and the rest of the algorithms in the \(\text{MRI}\) family). Unfortunately not only is \(\text{MRI}(0)\) not optimal, it cannot attain a constant competitive ratio.

**Lemma 7** The competitive ratio of \(\text{MRI}(0)\) is not smaller than \(\Omega(\sqrt{\ell})\).

**Proof:** For simplicity, we start with a lower bound of 3 and then note how to extend it to the higher lower bound as stated in the lemma. Assume that the initial list, of \(\ell\) items is \((x_1,x_2,...,x_{\ell-1},a)\). The initial segment, \(\sigma_0\), of the nemesis request sequence, \(\sigma\), is \(\sigma_0 = a,x_{\ell-1},x_{\ell-2},...,x_1\). Notice that after processing \(\sigma_0\) \(\text{MRI}(0)\) returns to the above initial configuration (and now each item was requested once). The rest of \(\sigma\) consists of an arbitrary number of repetitions of the following segment

\[
\sigma_1 = (x_{\ell-1},a,x_{\ell-1}), (x_{\ell-2},a,x_{\ell-2}),..., (x_1,a,x_1).
\]

For each \(i = \ell - 1, \ell - 2, ..., 1\), the item \(x_i\) will be brought by \(\text{MRI}(0)\) to the front only after the second request for \(x_i\) in the subsequence \((x_1,a,x_i)\) is processed. The element \(a\) will always be left at the back of the list. Clearly, after servicing \(\sigma_1\) the list maintained by \(\text{MRI}(0)\) returns to the initial configuration. The cost incurred by \(\text{MRI}(0)\) for the initial segment \(\sigma_0\) is some constant \(C = \ell^2\) and the cost of servicing the segment \(\sigma_1\) is \((\ell - 1)(3\ell - 2) = 3\ell^2 - 5\ell + 2\). Consider an offline algorithm \(\text{OPT}'\) that serves \(\sigma\) as follows. After the first request for \(a\), \(\text{OPT}'\) brings \(a\) to the front and then it keeps the list static forever. That is, each subsequent request for an item costs \(\text{OPT}'\) the position of the item in the following list

\[
(a,x_1,x_2,...,x_{\ell-1}).
\]

Thus, the cost incurred by \(\text{OPT}'\) for the initial segment \(\sigma_0\) is some constant \(D = \ell + \sum_{2 \leq i \leq \ell} i\) and the cost to serve the segment \(\sigma_1\) is \(\ell - 1 + 2 \cdot \sum_{2 \leq i \leq \ell} i = \ell^2 + 2\ell - 3\). The costs ratio, online to offline, for the segment \(\sigma_1\) is thus \((3\ell - 2)/(\ell + 3)\) which approaches 3 as \(\ell\) grows.

This idea can be carried further. We now describe the following straightforward generalization of the segment \(\sigma_1\) that will yield a nemesis request sequence that will force a competitive ratio of at least \(\Omega(\sqrt{\ell})\). Assume that the initial order of \(\text{MRI}(0)\)'s list is

\[
(x_1,x_2,...,x_{\ell-k},a_1,a_2,...,a_k),
\]

and that of \(\text{OPT}'\) is

\[
(a_1,a_2,...,a_k,x_1,x_2,...,x_{\ell-k}),
\]

where \(1 \leq k \leq \ell - 1\). These initial configurations can be obtained after a fixed initial segment requesting all items. The repetition is now on the segment

\[
(x_{\ell-k},a_1,a_2,...,a_k,x_{\ell-k}),...,(x_1,a_1,a_2,...,a_k,x_1).
\]

Here again, after completion of this segment \(\text{MRI}(0)\)'s list returns to the initial configuration and \(\text{OPT}'\) keeps its list static at the initial configuration. The cost incurred by \(\text{MRI}(0)\) for this segment is

\[
\frac{\ell - k}{2} \left( 4\ell + 2\ell k - k^2 - 3k \right).
\]

The cost incurred by \(\text{OPT}'\) for this segment is

\[
\frac{k}{2} \left( \ell k + \ell - k^2 - 3k \right) + \ell^2 + \ell - k.
\]
By differentiating the costs ratio (online to offline) with respect to $k$ it is possible to see that the maximum ratio is obtained at

$$k^* = \left(2\ell^2(\ell + 1) + 3\ell + 1\right)^{1/2} / \ell - 3 - 1/\ell.$$ 

Substituting $k^*$ for $k$ in the expression for costs ratio results in a function of $\ell$ that can be bounded below by $\Omega(\sqrt{\ell})$. 

The true competitive ratio of $\text{MRI}(0)$ remains an open question but we conjecture that it is indeed $\Theta(\sqrt{\ell})$. We note that the competitive ratio of one of the most conservative (yet “reasonable”) algorithms called \textsc{transpose} is $\ell/3$ [21].

5 Extensions to the dynamic model

Theorem 1 can be extended to the dynamic (standard) list accessing model [21, 8]. In this model a request is either an \textit{insertion} of an item, an \textit{access} of an item, or a \textit{deletion} of an item. An access or deletion of an item positioned $i$th from the front cost $i$ whereas an insertion of an item to a list currently holding $\ell$ items costs $\ell + 1$. This insertion cost implicitly requires that a new item is inserted at the back of the list (but of course, the new item can then move, using free exchanges, to any position closer to the front).

Each of the algorithms $\text{MRI}(m)$ is naturally extended to handle deletions and insertions. Depending on the exact definition of $\text{MRI}(m)$, in particular, how it deals with first requests for items, this extension is done in a straightforward manner. In accordance with the original definition of $\text{MRI}(m)$ we require that each new item is inserted at the front of the list.

\textbf{Theorem 2}: For each $m \geq 1$ $\text{MRI}(m)$ is $(2 - 1/\ell)$-competitive in the dynamic model, where $\ell$ is the number of items inserted.

\textbf{Proof}: The extension of Theorem 1 to this dynamic model is easily established by proving that for each insertion and deletion the amortized cost for $\text{MRI}(m)$ is within a factor $2 - 1/\ell$ of the actual cost incurred by $\text{FOPT}$ where $\ell$ is the total number of insertions (starting from an empty list). Consider a request for an insertion of an item $x$. Suppose that at this stage there are exactly $\ell' \geq 2$ items on the list. Since the cost of an insertion in the dynamic model is $\ell' + 1$ we can interpret it as if both $\text{OPT}$ and $\text{MRI}(m)$ first insert $x$ at the back of their lists where for $\text{FOPT}$, which contains $\ell' \geq 2$-item lists before the insertion, we add $\ell'$ new 2-item lists, $L_{x, z}$, one for each item $z$ that was on the list before this request. In each of these 2-item lists $x$ appears on the back (i.e. second).

At this stage there are no inversions corresponding to $x$ but new inversions can be created by $\text{FOPT}$’s move that may move $x$ forward, using free transpositions, in some number $k$ of its 2-item lists. Each of the new $k$ inversions is clearly of weight 1 since a subsequent request for $x$ will cause $\text{MRI}(m)$ to move $x$ to the front. Further, the maximum number of such new inversions is $\ell'$, the number of new 2-item lists containing $x$. Since $\ell' + 1$ is the actual cost (of both $\text{MRI}(m)$ and $\text{FOPT}$), the amortized cost for $\text{MRI}(m)$ is in the worst case

$$\ell' + 1 + \Delta \Phi = \ell' + 1 + k \leq 2\ell' + 1 = (2 - 1/\ell')(\ell' + 1) \leq (2 - 1/\ell')(\ell' + 1).$$

The analysis of the case of a request for deletion of an item $x$ is even simpler because all old inversions with respect to $x$ are eliminated and no new inversions are created. (Note that in this case we remove from the set $\text{FOPT}$ all the 2-item lists containing $x$.) 

\textsuperscript{11} The trivial cases where $\ell' = 0, 1$ should be treated separately but do not bear any special difficulty.
6 An experimental study of list accessing algorithms

In this section, we give an introduction to the experimental part of the paper. We specify the set of algorithms tested and shortly outline the experiments we conducted. Detailed descriptions of these experiments will then be given in the corresponding Sections 7 and 8 of the paper.

6.1 Algorithms

We now describe the algorithms we tested. In the description of most algorithms we specify the algorithm’s action only with respect to an ACCESS request. Unless otherwise specified, it is implicitly assumed that an INSERT request for an item \( x \) places \( x \) at the back of the list, and then \( x \) is treated as if it was accessed. With respect to each algorithm we also specify bounds on its competitive ratio whenever they are known. In the sequel \( \ell \) denotes the maximum number of items present in the list at any point in time.

6.1.1 Deterministic algorithms

Algorithm \textsc{move-to-front (MTF)} is one of the most well known and used algorithms. This algorithm attains an optimal competitive ratio of \( 2 - 2/(\ell + 1) \) [21, 12].

**Algorithm MTF:** Upon an access for an item \( x \), move \( x \) to the front.

Algorithm \textsc{transpose (TRANS)} is perhaps the most “conservative” algorithm presented here and is an extreme opposite to \textsc{MTF}. The competitive ratio of \textsc{TRANS} is bounded below by \( 2\ell/3 \) [21].

**Algorithm TRANS:** Upon an access to an item \( x \), transpose \( x \) with the immediately preceding item.

Algorithm \textsc{frequency-count (FC)} attempts to adapt its list to the empirical distribution of requests observed so far. A lower bound of \((\ell + 1)/2\) on its competitive ratio is known [21].

**Algorithm FC:** Maintain a frequency counter for each item. Upon inserting an item, initialize its counter to 0. After accessing an item increment its counter by one and then reorganize the list so that items on the list are ordered in non-increasing order of their frequencies.

In our implementation we further require that if two items have the same frequency count then the item requested less recently is positioned in front of the item requested more recently. The variant adopting the reverse of this ordering is denoted by \textsc{FC}'.

The following algorithm called \textsc{MTF2} is a more “relaxed” version of \textsc{MTF}. \textsc{MTF2} can be shown to be 2-competitive.

**Algorithm MTF2:** Upon the \( i \)th request for an item \( x \), move \( x \) to the front if and only if \( i \) is even.

Algorithm \textsc{move-ahead}(k) (\textsc{MHD}(k)) proposed by Rivest [19] is a simple compromise between the relative extremes of \textsc{TRANS} and \textsc{MTF}.

**Algorithm MHD(k):** Upon a request for an item \( x \), move \( x \) forward \( k \) positions.

Thus algorithm \textsc{MHD}(1) is \textsc{TRANS}. We have tested \textsc{MHD}(k) for \( k = 2, 4, 8, 16, 32, \ldots, 1024 \).

Algorithm \textsc{move-fraction}(k) (\textsc{MF}(k)) proposed by Sleator and Tarjan is a slightly more sophisticated compromise between \textsc{TRANS} and \textsc{MTF}. For each \( k \), algorithm \textsc{MF}(k) is \( 2k \)-competitive [21].

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Algorithm MF(k): Upon a request for an item \( x \) currently at the \( i \)th position, move 
\( x \) \( \lceil \frac{i}{k} \rceil - 1 \) positions towards the front.

Thus, algorithm \( \text{MF}(1) \) is \( \text{MTF} \). The algorithms of the \( \text{MF}(k) \) family as described above have the 
weakness that they do not perform any update operation upon an access for one of the first \( k \) items 
in the list. Therefore, we included in the experiments a variant \( \text{MF}'(k) \) treating the first \( k \) items 
in its list as a "\( \text{MTF} \)-cache". The algorithm \( \text{MF}'(k) \) behaves just like \( \text{MF}(k) \), but upon a request for 
one of the first \( k \) items in the list, the requested item is moved to the front. We have tested the 
algorithm \( \text{MF}(k) \) and \( \text{MF}'(k) \) for \( k = 2, 4, 8, 16, \ldots, 1024 \).

Algorithm \( \text{TIMESTAMP} (\text{TS}) \) due to Albers is an optimal algorithm attaining a competitive ratio 
of 2. \([1]\)

Algorithm \( \text{PRI}(m) \): Upon a request for item \( x \), insert \( x \) in front of the first (from the 
front of the list) item \( y \) that precedes \( x \) on the list and was requested at most once since 
the last request for \( x \). Do nothing if there is no such item \( y \), or if \( x \) has been requested 
for the first time.

The following family of algorithms is the PRI FAMILY (introduced in Section 2.2). As discussed 
earlier, for each \( m \geq 2 \) \( \text{PRI}(m) \) is 3-competitive and \( \text{MRI}(1) \) is 2-competitive.

Algorithm \( \text{MRI}(m) \): Upon a request for item \( x \), move \( x \) forward just in front of the 
first item \( z \) on the list that was requested at most \( m \) times since the last request for \( x \). 
Do nothing if there is no such item \( z \). If this is the first request for \( x \), leave \( x \) in place 
(move \( x \) to the front).

Notice that modulo the handling of first requests, algorithm \( \text{PRI}(1) \) is identical to algorithm \( \text{TS} \).
Also, as noted above, the limit element of this family, as \( m \) grows, is \( \text{MTF} \). We have tested the 
algorithm \( \text{PRI}(m) \) with \( m = 0, 1, \ldots, 8 \) and with the insertion position being the last and the front. 
In the sequel each member of the PRI family, \( \text{PRI}(m) \), that inserts a new item at the first (resp. 
last) position is denoted \( \text{PRI}'(m) \) (resp. \( \text{PRI}(m) \)).

The following family of algorithms is the PRI FAMILY introduced in Section 2.1). For each \( m \geq 1 \) 
algorithm \( \text{MRI}(m) \) is 2-competitive and is thus optimal. The competitive ratio of algorithm \( \text{MRI}(0) \) 
is bounded below by \( \Theta(\sqrt{\ell}) \).

Algorithm \( \text{MRI}(m) \): Upon a request for item \( x \), move \( x \) forward just after the last 
item \( z \) on the list that is in front of \( x \) and that was requested at least \( m + 1 \) times since 
the last request for \( x \). If there is no such item \( z \) move \( x \) to the front. If this is the first 
request for \( x \), leave \( x \) in place (move \( x \) to the front).

Recall that \( \text{MRI}(1) \) is equivalent to algorithm \( \text{TS} \) (modulo first requests for items). We have tested 
the algorithms \( \text{MRI}(m) \) with \( m = 0, 1, \ldots, 8 \) and with the insertion position being the last and the front. 
In the sequel each member of the MRI family, \( \text{MRI}(m) \), that inserts a new item at the first (resp. 
last) position is denoted \( \text{MRI}'(m) \) (resp. \( \text{MRI}(m) \)).

6.1.2 Randomized algorithms

Algorithm \( \text{SPLIT} \) (\( \text{SPL} \)) due to Irani \([12]\) was the first randomized algorithm that was shown to 
attain a competitive ratio lower than the deterministic lower bound of \( 2 - 2/(\ell + 1) \). It is known 
that \( \text{SPL} \) is \( 31/16 \)-competitive (\( = 1.9375 \)).

15
Algorithm SPL: For each item $x$ on the list maintain a pointer $p(x)$ pointing to some item on the list. Initially set $p(x) = x$. Upon a request for an item $x$, with probability $1/2$ move $x$ to the front and with probability $1/2$ insert $x$ just in front of $p(x)$. Then set $p(x)$ to point the first item on the list.

Algorithm BIT due to Reingold and Westbrook [17] attains a competitive ratio of $1.75 - 1.75/\ell$.

Algorithm BIT: For each item on the list maintain a mod-2 counter $b(x)$ initially set to either 0 or 1 randomly, independently and uniformly. Upon a request for an item $x$ first complement $b(x)$. Then if $b(x) = 0$ move $x$ to the front.

The following algorithm called RMTF is very similar to BIT but somewhat surprisingly its worst case performance is inferior. It can be shown that its competitive ratio is not smaller than 2 [24].

Algorithm RMTF: Upon a request for $x$, with probability $1/2$ move $x$ to the front, and with probability $x$ leave $x$ in place.

The algorithm RMHD is a simple randomized relative of the deterministic MHD family.

Algorithm RMHD: Upon a request for an item $x$ currently at the $i$th position, randomly choose a position from the set $\{1, \ldots , i\}$ and move $x$ to that position.

The family of algorithms COUNTER$(s, S)$ (CTR$(s, S)$) due to Reingold, Westbrook and Sleator [18] is a sophisticated generalization of algorithm BIT. Let $s$ be a positive integer and $S$, a nonempty subset of $\{0, 1, \ldots , s - 1\}$.

Algorithm CTR$(s, S)$: For each item $x$ on the list maintain a mod $s$ counter $c(x)$, initially set randomly, independently and uniformly to a number in $\{0, 1, \ldots , s - 1\}$. Upon a request for an item $x$, decrement $c(x)$ by 1 (mod $s$) and then if $c(x) \in S$ move $x$ to the front.

Thus, CTR$(2, \{1\})$ is BIT. Reingold et al. prove that CTR$(7, \{0, 2, 4\})$ is $85/49$-competitive ($\approx 1.735$). From this family we have tested algorithm CTR$(7, \{0, 2, 4\})$.

The family of algorithms RANDOM-RESET$(s, D)$ (RST$(s, D)$) due to Reingold et al. [18] is a variation on the COUNTER algorithms. Let $s$ be a positive integer and $D$, a probability distribution on the set $S = \{0, 1, \ldots , s - 1\}$ such that for $i \in S$, $D(i)$ is the probability of $i$.

Algorithm RST$(s, D)$: For each item $x$ on the list maintain a counter $c(x)$, initially set randomly a number in $i \in \{0, 1, \ldots , s - 1\}$ with probability $D(i)$. Upon a request for an item $x$, decrement $c(x)$ by 1. If $c(x) = 0$ then move $x$ to the front and then randomly reset $c(x)$ using $D$.

The best RST$(s, D)$ algorithm, in terms of the competitive ratio, is obtained with $s = 3$ and $D$ such that $D(2) = (\sqrt{3} - 1)/2$ and $D(1) = (3 - \sqrt{3})/2$. The competitive ratio attained in this case is $\sqrt{3} \approx 1.732$. In this family we have only tested this algorithm.

Let $p \in [0, 1]$ The following is family of algorithm called TIMESTAMP$(p)$ (TS$(p)$) due to Albers [1] that is a kind of randomized combination of algorithm TS and MTF. For each $p$, TS$(p)$ is proven to be $\max\{2 - p, 1 + p(2 - p)\}$-competitive.

Algorithm TS$(p)$: Upon a request for an item $x$, with probability $p$ execute (i) move $x$ to the front; and with probability $1 - p$ execute (ii) let $y$ be the first item on the list such that either (a) $y$ was not requested since the last request for $x$; or (b) $y$ was requested exactly once since the last request for $x$ and that request for $y$ was served by the algorithm using step (ii). Insert $x$ just in front of $y$. If there is no such $y$ or if this is the first request for $x$ leave $x$ in place.
The optimal choice is easily shown to be \( p = (3 - \sqrt{5})/2 \) in which case the competitive ratio attained is the golden ratio \( \phi = (1 + \sqrt{5})/2 \approx 1.62 \). From this family we have tested this algorithm and denote it by \( \text{TSP} \).

In [3], Albers, von Stengel and Wechner present the following algorithm called \( \text{COMB} \) which is a probability mixture of \( \text{BIT} \) and \( \text{TS} \). Algorithm \( \text{COMB} \) is shown to be \( 8/5 \)-competitive. To date this bound is the best known for a list accessing algorithm.

**Algorithm \( \text{COMB} \):** Before serving any request choose algorithm \( \text{BIT} \) with probability \( 4/5 \), and algorithm \( \text{TS} \) with probability \( 1/5 \). Serve the entire request sequence with the chosen algorithm.

Although for any data set the empirical performance of \( \text{COMB} \) can be determined from the performances of \( \text{BIT} \) and \( \text{TS} \), we have tested \( \text{COMB} \) separately, as a control for the statistical significance of our tests of randomized algorithms.

### 6.1.3 A Benchmark algorithm

In order to have a reference result we tested the performance of the following "bad" algorithm, \( \text{MTL} \), which acts in a way that seems to be the worst possible.

**Algorithm \( \text{MTL} \):** Upon a request for an item \( x \) move \( x \) to the back of the list.

Although the model requires that we charge \( \text{MTL} \) for the paid exchanges it performs we ignored these costs and only counted access costs.

### 6.2 Experiment 1: Access cost performance

In the access cost experiment, we made the algorithms serve several types of request sequences starting on an empty list. The goal was to rank the access cost performance of the various algorithms within the traditional dynamic model. The algorithms’ performance was measured with respect to the full-cost model where an access to the \( i \)th item in the list is charged \( i \). To obtain statistically significant results for the randomized algorithms, we averaged their results over 16 executions of each experiment. \(^1\)

We examined:

- Request sequences produced by memoryless sources according to Zipf’s law;
- Request sequences produced by Markov sources in order to examine the influence of locality;
- Request sequences extracted from the Calgary Corpus [5] (see Section 8.2).

We used the data type \texttt{random source} of the LEDA library [16] to produce uniformly distributed random numbers. The access cost experiment is discussed in detail in Section 7.

\(^1\)We computed 98% confidence intervals for the compression experiment we conducted. Just in one case two confidence interval did intersect. In all cases the intervals were very narrow such that our qualitative results holds for any mistake in the confidence interval.
6.3 Experiment 2: Compression performance

In the compression experiment, we measured the algorithms’ performance as data compressors in the compression scheme of Bentley et al. [7]. The algorithms were ranked according to the compression ratio they obtained on the Calgary Corpus [5], a data set designed to test the performance of text compression algorithms. We examined both a byte-level and a word-level variant of this compression scheme. Here again the results for the randomized algorithms were averaged over 16 executions. The compression experiment is discussed in detail in Section 8.

7 Experiment 1: Access cost performance

7.1 Previous experimental studies

In this section, we describe our experiment for testing the access cost performance of online list-accessing algorithms. A few such empirical studies have been conducted in the past.

Bentley and McGeoch [6] tested the performance of MTF, FC, TRANS with respect to request sequences generated from several text files (4 files containing Pascal programs and 6 other English text files). The sequences generated from the text files by parsing the files to “words” with a word defined as an “alphanumeric string delimited by spaces or punctuation marks”. It was found that FC is always superior to TRANS and that MTF is often superior to FC. Tenenbaum [23] tested the performance of various algorithms from the MOVE-AHEAD(k) family (MHA(k)) with respect to request sequences distributed by Zipf’s law. A few other simulation results testing various properties of particular algorithms with respect to sequences generated via Zipf’s distribution are summarized in a survey by Hester and Hirschberg [11].

7.2 Request sequences distributed by Zipf’s law

7.2.1 Zipf sequences: description

In the first access cost experiment, we carry on the studies of Tenenbaum [23] and Hester and Hirschberg [11] and test our more extensive set of online list accessing algorithms on request sequences distributed by Zipf’s law. Given m distinct items, Zipf’s law assigns to the i-th item the probability

\[ p_i := \frac{1}{i \cdot H_m} \text{ for } 1 \leq i \leq m, \]

where \( H_m = \sum_{j=1}^{m} \frac{1}{j} \) is the m-th Harmonic number and serves to normalize the sum of probabilities to 1. The requested items are selected independently according to this distribution.

7.2.2 Zipf sequences: discussion of results

We performed the access cost experiment for the values \( m = 8, 16 \) and 32 on request sequences of length \( 10^6 \). The detailed results of in terms of cost ratios can be found in Table 4 in Appendix D.

The results for the different values of \( m \) are similar. We observe that more conservative algorithms seem to be favored. The most conservative algorithm in both cases is FC, and this algorithms indeed performs best. After a certain time, FC will almost certainly have ordered its list according to the given probability distribution and will not perform any update operations any more. Recall that FC is not optimal and not even competitive.

Interesting observations can be made for the families MRR(m) and PRR(m). First, we observe that MRR(m) always outperforms PRR(m). Secondly, both families exhibited consistent and perfect
monotonicity in terms of their performance as a function of the parameter \( m \). The algorithms \( \text{MR}(0) \) and \( \text{PR}(0) \) achieved the best performance in their families. We observe a considerable increase in costs between \( \text{MR}(0) \) and \( \text{MR}(1) \).

The costs of the algorithms of the \( \text{MHD}(k) \) class increase with \( k \). Again, more careful (or conservative) behavior is rewarded. We observe that the extrem member \( \text{MTR} \) of this class is among the worst performing algorithms on all examined sequences. On the other hand, \( \text{TRANS} \) (which is equivalent to \( \text{MHD}(1) \)) is always one of the best algorithms.

There is no consistent behaviour of the algorithms of the \( \text{MF}(k) \) family. Indeed, different Zipf sequences (among those presented here, but also others) yielded very different results. The reason is that these algorithms do not update the front of their list, and therefore their performance depends strongly on the first requested items. As for the members of the variant family \( \text{MF}'(k) \), these algorithms perform well, as long as the \( \text{MTR} \)-cache remains small.

Finally, the randomized algorithm have considerably higher costs than the best deterministic algorithms in all cases, and they mostly appear at the end of the field. These results stand in strong contrast to known analyses of randomized algorithms which say that randomization can yield algorithms with a competitiveness below the deterministic lower bound of \( 2 \). However, we should recall that in competitive analysis, requests are produced by an adversary whose goal is to increase the algorithm’s costs with respect to an optimal offline algorithm. This includes that a request may depend on the algorithm’s reactions on former requests, and in this case randomization on the algorithm’s side may make the adversaries life more difficult. However in this experiment, request sequences are generated independently from each other without memory. Therefore, there is no reason to expect that the competitive results will be applicable here, and in particular that randomization will give any advantage.

7.3 Request sequences produced by Markov sources

7.3.1 Markov sequences: description

We say that a request sequence exhibits “locality of reference”, if the number of distinct requested items in a small part of the sequence is considerably smaller than the number of distinct items in the entire sequence, or alternatively, if requests depend strongly on immediately preceding requests. It is clear that the degree of locality in the request sequence must have a considerable influence on the performance of online algorithms, depending on how quickly they adapt to local changes in the request sequence. In the second access cost experiment, we want to examine this influence.

We use a simple probabilistic model to produce request sequences with different degrees of locality. The model is based on Markov sources. A Markov source consists of a set of \( m \) states and is described by a transition matrix

\[
(p_{\mu \nu})_{\mu, \nu = 1, \ldots, m} \quad \text{where} \quad p_{\mu \nu} \geq 0 \quad (1 \leq \mu, \nu \leq m) \quad \text{and} \quad \sum_{\nu=1}^m p_{\mu \nu} = 1 \quad (1 \leq \mu \leq m).
\]

Thus each line of the transition matrix gives a probability distribution, and if the Markov source is in state \( \mu \), the probability that it is goes to state \( \nu \) is exactly \( p_{\mu \nu} \). The initial state may again be chosen according to an initial distribution.

We now describe the Markov source used to generate request sequences with different degrees of locality. The source will request the item \( \mu \), if it is in state \( \mu \). Let \( k, n \in \mathbb{N} \). The Markov source has \( m = k \cdot n \) states which are partitioned in \( k \) disjoint \( n \)-element sets \( S_i \)

\[
S_i := \{(i - 1) \cdot n + 1, \ldots, i \cdot n\}.
\]
We will call these sets the local sets. In order to receive request sequences with locality, the Markov source should have the following property. Once it enters a local set $S_i$, it is to stay there for a certain time before entering a new local set $S_j$ ($i \neq j$). The degree of locality is varied by a parameter $\alpha$ ($0 < \alpha < 1$) denoting the probability that the next request is in the current local set.

It remains to specify the exact transition probabilities. For reasons of simplicity, we use a fixed probability distribution $(q_1, \ldots, q_n)$ where $q_j > 0$ for all $1 \leq j \leq n$. The probability that the $j$th smallest state in a local set is entered on the next request will be proportional to $q_j$. Let $Q$ be the $(n \times n)$-transition matrix where all lines are identical to the vector $(q_1, \ldots, q_n)$. We are now ready to define the $(k \cdot n \times n)$-transition matrix $P$ of our Markov source:

$$
P := P(k, n, \alpha, q_1, \ldots, q_n) := \begin{pmatrix}
\alpha Q & \frac{1-\alpha}{k-1} Q & \cdots & \frac{1-\alpha}{k-1} Q \\
\frac{1-\alpha}{k-1} Q & \alpha Q & \cdots & \frac{1-\alpha}{k-1} Q \\
\vdots & \vdots & \ddots & \vdots \\
\frac{1-\alpha}{k-1} Q & \frac{1-\alpha}{k-1} Q & \cdots & \alpha Q
\end{pmatrix}
$$

(6)

It is easy to verify that, by our choice of $\alpha$ and the $q_j$, all entries in $P$ are non-negative and that the entries along each line of $P$ sum up to 1, i.e. $P$ is a valid transition matrix. Furthermore, we see that the probability for the source to stay in its current local set is exactly $\alpha$.

The simple probabilistic model just described can easily be generalized by varying the sizes of the local sets and the transition probabilities within and between the local sets. Before specifying the parameters used in our experimental study, we want to show some properties confirming that the above model is reasonable for abstraction of locality.

The theory of Markov chains tells us that if all entries of $P$ are positive, then the sequence $\{P^t\}_{t \geq 1}$ of transition matrixes converges towards a limiting matrix in which all lines are identical to a probability vector $(p_1, \ldots, p_m)$. This vector is called the stationary distribution of the Markov source. It is independent of the initial distribution and gives the probabilities for the occurrences of the states in an infinite sequence produced by the Markov source. The following Lemma 8 describes two important properties of our Markov source.

**Lemma 8** Let $k, n \in \mathbb{N}$, $0 < \alpha < 1$, and let $(q_1, \ldots, q_n)$ be a probability distribution with $q_j > 0$ for $1 \leq j \leq n$. Consider the Markov source with $m = k \cdot n$ states and the transition matrix $P$ as defined in equation (6).

1. The expected number of subsequent requests in a local set is $1/(1 - \alpha)$.

2. The stationary distribution $(p_1, \ldots, p_m)$ is given by

$$
p(i-1)n+j = \frac{q_j}{k} (1 \leq i \leq k, 1 \leq j \leq n).
$$

(7)

The proof of Lemma 8 can be found in Appendix C. The first part of the lemma confirms that the parameter $\alpha$ is an indicator for the degree of locality: the closer $\alpha$ is to 1, the longer the Markov source stays in a local set, thus producing a request sequence with stronger locality. The second part of the lemma reveals an interesting property of our Markov source, namely that the stationary distribution is independent of the parameter $\alpha$. This means that the frequencies of the requested items do not depend on the degree of locality in our request sequence. Only the number of request before a local set is left again varies with $\alpha$. Furthermore, we see from the periodicity of the vector $(p_1, \ldots, p_m)$ in equation (7) that our Markov source requests each local set with the same probability.
7.3.2 Markov sequences: discussion of results

For the experiment, we set $k = n = 4$ and chose the probabilities $q_j$ for the distribution $(q_1, \ldots, q_n)$ according to Zipf's law. The probability $\alpha$ was varied in order to examine the influence of locality. We produced request sequences of length $10^6$ for all values $\alpha = 0.1, 0.2, \ldots, 0.9$. The initial state was chosen at random. Table 5 in Appendix D presents the average access costs of all algorithms for the values $\alpha = 0.1, 0.5$ and 0.9. Figure 1 graphically presents the average access costs of some selected algorithms for all examined values of $\alpha$.

Let us first turn to Figure 1. We observe that the degree of locality has a considerable influence on the performance of many, but not all algorithms. The algorithm FC has about the same costs for all values of $\alpha$. After a certain time, its list will be ordered according to the limiting distribution which, as we have seen, is independent of $\alpha$, and FC serves the entire sequence without remarkable reorganisations of its list. The results for the other algorithms show that the locality in the sequences produced by our Markov source may have a positive influence on the algorithms’ performance. Their access costs decrease with increasing $\alpha$. This effect is particularly strong for MTF, which is the worst performing algorithm for $\alpha = 0.1$, but performs best for $\alpha = 0.9$. Figure 1 shows – and
this is confirmed by the tables in Appendix D - that \textit{fc} performs best while \( \alpha \leq 0.6 \). Only when the locality becomes very strong, \textit{fc} is outperformed by other algorithms reacting faster on local changes.

We now turn to the complete results summarized in the tables of Appendix D. We start with the case \( \alpha = 0.1 \) and make the following observations. The algorithm \textit{fc} performs best. The costs of the \textit{mhd}(k) algorithms increase with \( k \). The same holds for the algorithms of the \textit{mr}(m) and \textit{pr}(m) family when \( m \) increases. Furthermore, \textit{mr}(m) outperforms \textit{pr}(m) for each \( m \). The \textit{mp}'(k) family performs well as long as \( k \) is relatively small. All randomized algorithms perform considerably worse than the best deterministic algorithms.

In the case \( \alpha = 0.5 \), \textit{fc} is still the best algorithm, however its lead over all other algorithms has decreased; the costs of the worst algorithm are only 15 \% higher. The algorithms of the \textit{mhd}(k) family still appear in order of \( k \). Still \textit{mr}(m) outperforms \textit{pr}(m) for each \( m \), but for both families the members for extreme values of \( m \) have higher costs than the members for modest values of \( m \) like \( 2 \leq m \leq 5 \). Again the \textit{mp}'(k) family performs well for \( k \). All randomized algorithms appear at the end of the list, without exception having higher costs than \textit{mtf} which is the second worst performing deterministic algorithm.

Let us now consider the interesting case of \( \alpha = 0.9 \), where we have a strong locality in our request sequence. We observe that the results in this case are extremely different from the results for the other values of \( \alpha \), and in some parts are even turned to the opposite. The algorithm \textit{fc} is now among the worst algorithms, and its costs are more than 42 \% over the costs of the now best performing algorithm \textit{mtf}. The algorithms of the families \textit{mhd}(k), \textit{mr}(m) and \textit{pr}(m) now appear ordered by decreasing \( k \) or \( m \), respectively. Furthermore, \textit{pr}(m) outperforms \textit{mr}(m) for each considered value of \( m \). This time the members of \textit{mp}'(k) family show a relatively poor performance, whereas the randomized algorithms yield relatively good results.

The Markov model we used in this section to examine the influence of locality is certainly arguable. However, it is simple, and we were able to show some properties indicating that it is a reasonable abstraction of locality. In any case, the model was sufficient for our purposes, namely to illustrate that the ranking of list accessing algorithm depends strongly on properties of the served request sequence.

### 7.4 Request sequences extracted from the Calgary Corpus

In the third and last access cost experiment, we extracted request sequences from some files of the Calgary Corpus, basically following the approach of Bentley and McGeoch [6] who extracted request sequences from several Pascal and text files. More precisely, we extracted five sequences from each of the two corpus files \texttt{book1} and \texttt{geo} which are qualitatively rather different. Whereas \texttt{book1} contains pure English text and thus numerous repeating substrings, \texttt{geo} is a concatenation of 32-bit numbers. The first extracted sequence is the file itself, i.e. each individual byte is considered a request. For the second sequence, we considered each byte modulo 16, thus obtaining a related sequence producing a shorter list. The remaining sequences were obtained by application of the Burrows-Wheeler transformation [9] (BW transformation for short). For a finite input string, the BW transformation calculates a permutation in which there usually is a strong locality. We obtained the third request sequence by application of the BW transformation on the raw corpus file. The forth sequence was obtained from the third sequence by replacing each run of subsequent requests on the same item by one single request on that item. Finally, the fifth sequence was obtained by taking each byte in the forth sequence modulo 16. Table 2 shows the length and numbers of distinct items in the resulting request sequences. We decided to include the “projected” (modulo
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<td>16</td>
</tr>
</tbody>
</table>

Table 2: Lengths and numbers of distinct items in the request sequences extracted from the Calgary corpus.

16) sequences in the experiment, because the “raw”, unprojected sequences produce rather long lists, and this setting is rather untypical for linear-list applications. However, the results indicate that there is relation between the projected and unprojected sequences.

The raw results of the access cost experiment on the request sequences extracted from the Calgary Corpus are summarized in Tables 6 and 7 of Appendix D.

8 Experiment 2: Compression performance

8.1 Description of the compression algorithm

Bentley et al. [7] proposed a compression scheme based on online list accessing algorithms. In this scheme, all possible symbols (e.g. characters or words) occurring in the input string are stored in a linear list. Whenever a symbol is to be encoded, a binary encoding of its current list position is transmitted (using some variable length prefix-free code). Before the next symbol is encoded, the list is reorganized by a list accessing algorithm. If the symbol is not in the list, it has to be transmitted specifically. To restore the data, the receiver performs the inverse operations. That is, the receiver can recover each symbol whose location was transmitted and updates its symbol list using the same list accessing algorithm. As the receiver has no knowledge about locations transmitted in the future, the list accessing algorithm has to work online. In the experiment described in this section, we tested the performance of all algorithms in a byte- and a word-level variant of the Bentley et al. compression scheme.

In the byte-level experiment, we start with a full list storing all 256 characters of the ASCII character set. Thus, we need a prefix-free code providing 257 codewords for the possible list positions and an additional end-of-file symbol. We performed the byte-level experiment with several variable length prefix-free encodings including Elias, δ-encoding, ω-encoding and several start-step-stop encodings. A brief description of these schemes can be found in Appendix E. The best results were obtained with a (2, 2, 8)-start-step-stop code improved by the phasing technique (see Table 8 in Appendix E).

In the word-level experiment, two disjoint word sequences are extracted from the input sequence. We denote all characters of the ASCII character set for which the C-library function is space returns a non-zero value as space characters. All other characters are called non-space characters. A space word then is a maximum length sequence of subsequent space characters between two non-space characters. Analogously, a non-space word is a maximum length sequence of subsequent non-space characters between two space characters. We use two initially empty word-lists which can have arbitrary length. The first list stores all space words, the second list stores all non-space words. In the input sequence, space words and non-space words alternate, and the next word is always
encoded by its current position in the corresponding list using some prefix-free code. If a new word
is encountered and \( \ell \) is the current length of the list, we encode the list position \( \ell + 1 \), thus switching
into a character mode to transmit the characters of the new word. Here again, we use two lists, one
for space characters and one for non-space characters. Furthermore, both lists contain an escape
character to encode the end of the new word. After encoding the end of the new word, we switch
back into word mode, and the new word is inserted in the word list according to the applied list
accessing algorithm. To encode the end of the input sequence, we switch into character mode and
then immediately back into word mode (this can be viewed as transmitting an empty word). All
four lists are managed by the same list accessing algorithm. We use an Elias code to encode the
positions in the space word list, and a \( \ell \)-code to encode the positions in the non-space word list.
We developed two special codes to encode the positions in the 7-element space character and the
251-element non-space character list. These two codes are described in Appendix E.

In both variants of the Bentley et al. compression scheme, we are only interested in measuring the
compression performance and ignore space and time complexity issues. Also none of the algorithms
was actually implemented to compress and decompress data. However, both settings are completely
realistic from a practical point of view, because they take into account everything that is necessary
to compress and decompress the data. In particular, we charge the costs contributed by escape
symbols in our settings. This is often neglected, but we consider escape symbols an essential part
of the compressed representation of an input sequence.

8.2 The data set

Exact analyses of compression algorithms are difficult, because they require a precise mathematical
description of the input source. Real data is usually too complex for such a description.

In the practical field of data compression, an algorithm's performance is usually measured
experimentally with respect to a benchmark corpus which is a relatively large data set supposed
to be representative for future inputs to the algorithm. Such benchmark data sets exist for various
fields of data compression such as text compression, or compression of images or audio data.

Bell, Cleary, and Witten [5] collected the Calgary Corpus. This corpus has become the standard
corpus for lossless compression algorithms. It consists of (mainly text) files from various application
fields including books, papers, numeric data, a picture, programs and object files. Descriptions
of the files can be found in [5]. Table 3 lists some properties of the corpus files.

Recently, Arnold and Bell [4] proposed the Canterbury Corpus as an alternative corpus for
lossless compression algorithms. The motivation for the new corpus was the fear of compression
algorithms being tuned for the standard corpus and the possibility of the Calgary Corpus being too
out-dated for today's applications. However, after having tested various compression algorithms
on the new corpus, the authors admit that there are no considerable qualitative differences in the
results obtained on the two data sets, and conclude that the Calgary Corpus is still appropriate to
measure the performance of compression algorithms.

8.3 Previous experimental studies

A few empirical tests of the performance of some list accessing algorithms applied to text compres-
sion have been conducted. Bentley et al. [7] tested the performance of mtp-compression algorithms
with various list ("cache") sizes with respect to several text files (containing several C and Pascal
programs, book sections and transcripts of terminal sessions). They also compared the algorithms’
performance with that of Huffman coding compression and found that for a sufficiently large cache
size (e.g. 256) mtp-compression is "competitive" with Huffman coding. Albers and Mitzenmacher
<table>
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<th>non-space words</th>
<th>space words</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>total</td>
<td>distinct</td>
<td>ratio</td>
</tr>
<tr>
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<td>111261</td>
<td>81</td>
<td>1373</td>
</tr>
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<td>book1</td>
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<td>9375</td>
</tr>
<tr>
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<td>610856</td>
<td>96</td>
<td>6363</td>
</tr>
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<td>400</td>
</tr>
<tr>
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<td>377109</td>
<td>98</td>
<td>3848</td>
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<tr>
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<td>256</td>
<td>964</td>
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<td>92</td>
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<td>87</td>
<td>823</td>
</tr>
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</tr>
<tr>
<td>trans</td>
<td>93695</td>
<td>99</td>
<td>946</td>
</tr>
</tbody>
</table>

Table 3: The Calgary Corpus. Total number of symbols, number of distinct symbols and the ratio between them with respect to byte- and word-parsing of the Calgary Corpus files. The corpus files can be downloaded from the ftp site ftp.cpsc.ucalgary.ca.

[2] compared the compression performance of TIMESTAMP and MTF with respect to the Calgary Corpus. They considered both word and byte (i.e. character) parsings. Using Elias encoding (see Appendix E), they obtained the following results. TIMESTAMP-compression is significantly better than MTF-compression with respect to byte parsing, but both are not “competitive” with standard Unix compression utilities. With respect to word parsing, TIMESTAMP is often (only marginally) better than MTF compression. The word-based compression performance of both these algorithms is found to be close to that of standard Unix compression utilities. However, note that the results of this experiment do not count the encoding of new words that are not already on the list. A few other studies compare the performance of particular, more sophisticated list accessing compressors that alter the basic scheme. Burrows and Wheeler [9] tested the performance of an MTF-compressor that operates on data that is first transformed via a “block-sorting” transformation. Grinberg et al. [10] tested the performance of a MTF-compressor that uses “secondary lists”. We note (based on their results and ours) that these more sophisticated schemes achieve in general better compression results than the basic scheme.

From the above, the only comparable studies are those of Bentley et al., and Albers and Mitzenmacher. First we note that our study supports the qualitative results of both these studies. However, they are not comparable quantitatively (the Bentley et al. study is incomparable to ours as it used a different corpus; the quantities reported in the Albers-Mitzenmacher study are incomparable to ours as they have not measured the transmission costs of new words).

Compared to the known empirical studies, the results reported here are significantly more comprehensive and provide insights into many algorithms, among which some that have never been tested.
8.4 Results of the compression experiment

The detailed results of the compression experiment can be found in Appendix F. Compression performance is usually measured in terms of the compression ratio which is the number of calculated output bits per input character. Tables 10 and 11 in Appendix F give the compression ratios achieved by all algorithms on each corpus file for the byte- and the word-level compression experiment, respectively.

Let us first turn to the byte-level compression experiment. Almost all list accessing algorithms indeed compress all input files, although the compression scheme is very simple and has no pre-knowledge about the input. Only some members of the $\mathbf{MF}(k)$ family expand some of the input files; these algorithms do not reorganize the front part of their lists. However, the compression performance of all algorithms is poor compared with standard compression programs such as compress and gzip. The best results are obtained by members of the families $\mathbf{MF'}(k)$ and $\mathbf{MHD}(k)$ for small values of $k$, $\mathbf{FC}$ and $\mathbf{MRI}(0)$ and $\mathbf{PRI}(0)$. Note that none of these algorithms is optimal or even competitive in terms of the competitive ratio. We observe that the members of the families $\mathbf{MF'}(k)$ and $\mathbf{MHD}(k)$ appear ordered by increasing $k$ (modulo some exceptions for small values of $k$). The same holds for the families $\mathbf{MRI}(m)$ and $\mathbf{PRI}(m)$ with increasing $m$. This is remarkable, because these algorithms have more knowledge about past requests (or symbols) for greater values of $m$, but apparently they cannot take an advantage of this knowledge (w.r.t. this data set). The $\mathbf{MRI}$ family seems to be superior to the $\mathbf{PRI}$ family: $\mathbf{MRI}(m)$ outperforms $\mathbf{PRI}(m)$ for all values of $m$. Another remarkable observation is a considerable decline of the compression performance between $\mathbf{MRI}(0)$ and $\mathbf{MRI}(1)$, as well as between $\mathbf{PRI}(1)$ and $\mathbf{PRI}(2)$. The algorithm $\mathbf{MTF}$ is among the worst performing algorithms.

We observe that the randomized algorithms perform considerably worse than the best deterministic ones. Algorithm $\mathbf{RMHD}$ is by far the best randomized algorithm. A striking fact is that the ranking of the randomized algorithms exactly matches their competitive ratio ranking. For the algorithm $\mathbf{COMB}$, it is important to mention that the best performance was consistently due to the deterministic algorithm $\mathbf{TIMESTAMP}$ and not to $\mathbf{BIT}$.

In the word-level compression experiment, we observe again that all algorithms compressed all input files (except for some $\mathbf{MF}(k)$ algorithms that could not compress the file $\text{pic}$). The compression performance is considerably better than in the byte-level compression experiment. This is because longer substrings are encoded by relatively short codewords on the text files of the Calgary corpus, where our word-parsing is natural. However, we observe that on those inputs where our word-parsing is not natural, namely the binary files of the corpus, the word-level performance may be worse than in the byte-level setting. The relative inadequacy of our setting for these files is supported by the following observation made for all algorithms. For the binary files, most of the output bits were contributed by the character lists, whereas the word lists added only a marginally small fraction (e.g. for algorithm $\mathbf{MTF}$ and file $\text{geo}$, the character lists produced about 97% of all output bits). During the compression of the text files however, the word and character lists contributed comparable fractions of bits to the output (e.g. for algorithm $\mathbf{MTF}$ and file $\text{bib}$, the character lists contributed about 42% of all output bits).

The best results are obtained by members of the $\mathbf{MF'}(k)$ family for small values of $k$, the $\mathbf{MRI}$ family (in particular $\mathbf{MRI}(0)$), $\mathbf{PRI}(0)$, $\mathbf{PRI}(1)$ (i.e. $\mathbf{TIMESTAMP}$) and $\mathbf{FC}$. Again the members of the families $\mathbf{MRI}(m)$ and $\mathbf{PRI}(m)$ appear ordered by increasing $m$, and we observe a considerable increase in cost between $\mathbf{MRI}(0)$ and $\mathbf{MRI}(1)$. For all considered values of $m$, $\mathbf{MRI}(m)$ outperforms $\mathbf{PRI}(m)$. In the word-level experiment however, the variants $\mathbf{MRI'}(m)$ and $\mathbf{PRI'}(m)$ which insert new items at the front have significantly higher costs than $\mathbf{MRI}(m)$ and $\mathbf{PRI}(m)$. The reason for this is the
fact that for all corpus files, more than half of the non-space words (and these dominate the costs) occur only once. Thus inserting a new word at the front of the list usually has the only effect of making the encoding of future words more expensive. The members of the \textit{MHD} family appear in the second part of the field only, with the extrem members \textit{MTF} and \textit{TRANS} (but also \textit{MHD}(2) and \textit{MHD}(1024)) ranking among the worst algorithms.

For the randomized algorithms, we make similar observations as in the byte-level experiment. Again, \textit{RMHD} is by far the best randomized algorithm and the ranking of the randomized algorithms almost matches their competitive ratio ranking (with the algorithms \textit{BIT} and \textit{CTR} being transposed in that ranking).

Finally we note that the results of this experiment support the qualitative results of the Albers-Mitzenmacher compression experiment [2]. Namely, the compression ratios obtained by algorithm \texttt{TIMESTAMP} were consistently better than those obtained by \texttt{MTF}-compression.

### 8.5 Some notes on the compression experiment

The word-level compression experiment shows that the Bentley \textit{et al.} compression scheme may yield good results, if it makes use of some prior knowledge about the structure of the input, as our word-level setting did by assuming text inputs and parsing the input file into words. On the other hand, if the input is not of the assumed structure, schemes depending on prior knowledge usually perform poorly. Our compression experiment illustrates this problem by the poor results obtained for the highly compressible corpus file \texttt{pic}. Note that if one expects a “universal” compression algorithm, that compresses well on average (i.e. averaged over all the inputs it will ever see), then the compression algorithms in our word-level setting are not acceptable. Examples of universal or more powerful compression algorithms are the Context-tree weighting method, Ziv-Lempel algorithms, the PPM (prediction by partial match) schemes, and the block-sorting algorithm. These algorithms usually achieve better compression ratios than our word-level compression setting, though the latter is already a rather complicated variant of the basic Bentley \textit{et al.} scheme.

### 9 Concluding remarks

The \texttt{MRI} family presented here exhibits some very attractive features. Nevertheless notice that the implementation of the algorithm \texttt{MRI}(m) is quite expensive in terms of time and memory. For the implementation of \texttt{MRI}(m) we need to maintain, for each item \(x\) on the list, an \(m\)-ary vector \(T_x\) containing the times (indices of requests) of the last \(m\) requests for \(x\).

This paper leaves some questions open. For instance, it remains to determine the competitive ratio of the algorithms in the \texttt{PRI} family. We conjecture that for each \(m > 0\) \texttt{PRI}(m) is 2-competitive.

Perhaps a more interesting goal would be to identify “the most conservative” algorithms that are still optimal thus expanding the set of optimal list accessing algorithms (with different characteristics) even more. Note that this question as stated is not well defined and in fact, one crucial step towards answering this question would be to define a meaningful measure of “conservatism”.

To our knowledge, our experimental study is the first one comparing a large number of different online list accessing algorithms. Even so few interesting algorithm were left aside, mainly because they were introduced to us after we conducted our experiments. Two such interesting families of algorithms were developed by Schulz [20]: \texttt{SORT-BY-RANK} and \texttt{SORT-BY DELAY}.

Some of the experimental results reported in this paper stand in contrast to various theoretical studies of the list accessing problem. In the case of the access cost experiment, the reader should
be aware that, because of the nature of the examined request sequences, our experimental results are hardly appropriate to support theoretical results obtained by competitive analysis.

In the access cost experiment, we tried to tie on previous experimental studies and to extend their results to our large algorithm set. In contrast to previous studies however, we also tried to cover a wider range of request sequences. The fact that we obtained quite different rankings for different request sequences indicates that, at least for the online list accessing problem, it is dangerous to restrict experimental studies to one particular class of input sequences. This may lead to false conclusions. We used an experimental approach to examine the influence of locality in request sequences on the performance of online list accessing algorithms. Our experiments show that the degree of locality has a considerable influence both on the algorithms' costs and on their ranking. It would be of major importance to devise a meaningful, quantitative measure of locality of reference that could be used to classify request sequences and further investigate the correlation between various algorithms and their performance with respect to sequences. To the best of our knowledge, no such measure has been studied. Also, it would be of great interest to put together an appropriate corpus that could be used to test the performance of data structures and algorithms for dictionary maintenance.

The results concerning compression performance clearly indicate that the list accessing compression scheme by itself will not give compression ratios that are competitive with popular compression algorithms such as those based on Lempel-Ziv schemes. Nevertheless, it is remarkable that a compression scheme as simple as the Bentley et al. scheme on byte-level is already capable of performing compression. Burrows and Wheeler [9] used the Bentley et al. scheme with MTF-encoding as backend for their very powerful block-sorting compression algorithm. For example, this method is used in the BZIP compression software. Our results in the access cost experiment with sequences generated by the BW scheme suggest that using other list accessing algorithms such as MF instead of MTF might yield even better results. Finally, the results of the access cost experiment suggest that it would be very interesting to experiment with dynamic transitions between different basic list accessing algorithms in order to adapt to changing levels of locality of reference.

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References


A Proof of Inequality (4) and Lemma 1

Denote by $\text{OPT}_{P_{xy}}^{*}(\sigma)$ the total cost incurred by $\text{OPT}$ for paid exchanges between $x$ and $y$ while serving $\sigma$. Then a very similar development to the one leading to identity (3) with the inclusion of the costs incurred by $\text{OPT}$ for paid exchanges easily yields

$$\text{OPT}^{*}(\sigma) = \sum_{\{x, y\} \subseteq L \atop x \not= y} \left[ \text{OPT}_{xy}^{*}(\sigma) + \text{OPT}_{P_{xy}}^{*}(\sigma) \right]$$  \hspace{1cm} (8)

Also, it is not hard to see that $\text{OPT}$ does not in general satisfy the Pairwise Property. Nevertheless, it can be easily shown that $\text{OPT}$ does satisfy the following inequality for every pair of items, $x$ and $y$

$$\text{OPT}^{*}(\sigma_{xy}) \leq \text{OPT}_{xy}^{*}(\sigma) + \text{OPT}_{P_{xy}}^{*}(\sigma),$$  \hspace{1cm} (9)

To prove this inequality notice that the right hand side of (9) gives the total cost of some offline (not necessarily optimal) algorithm that is a “projection” of $\text{OPT}$ over $x$ and $y$. Namely, this projected algorithm operates on $L_{xy}$ and serves the request sequence $\sigma_{xy}$ according to the relative order of $x$ and $y$ in $L$ as maintained by $\text{OPT}$ while serving $\sigma$. An optimal offline algorithm for the two-item list, whose total cost in serving $\sigma_{xy}$ is the left hand side of (9), surely pays no more than any other offline algorithm so the inequality must hold.

Equation (8) combined with inequality (9) yields inequality (4). That is,

$$\sum_{\{x, y\} \subseteq L \atop x \not= y} \text{OPT}^{*}(\sigma_{xy}) \leq \text{OPT}^{*}(\sigma).$$

The extension of inequality (4) to the full-cost model can be made using an extended cost function instead of $\text{ALG}(x, r_j)$. Define the following extended cost function $\text{ALG}(x, r_j)$,

$$\text{ALG}(x, r_j) = \begin{cases} 
1 + \frac{1}{c_i} & \text{if } x \text{ is in front of } r_j, \\
\frac{1}{c_i} & \text{if } r_j \text{ is in front of } x, \\
0 & \text{otherwise (} x = r_j \text{).} 
\end{cases}$$  \hspace{1cm} (10)

This cost function indirectly counts also the last (ith) comparison that must be counted in the full-cost model (that is, when we access the ith item). It is not hard to verify that with this extended cost function the equality (2) holds within the full-cost model. Analogous to $\text{ALG}_{xy}^{*}(\sigma)$, we now define $\text{ALG}_{xy}(\sigma)$ (using this extended cost function) and accordingly modify the equality (3), Equation (8), and the inequality (9). This proves Lemma 1.

B Proof of Lemma 6

Fix any request sequence $\sigma$. We prove by induction on $i$, the index of the ith request, that the invariant holds. The base case, $i = 1$, trivially holds. Assume the induction hypothesis for all $j < i$. We prove that the invariant holds for the ith request for an item $x$. (We refer to this request “the current request for $x$"; the previous request for $x$ is referred to as “the last request for $x$".) Consider the configuration of the list $L$ (of either MIN(1) or TIMESTAMP). Suppose, by contradiction, that the invariant does not hold. Let $y$ be the first element in $L$ that was requested less than twice since the last request for $x$. Let $z$ be the last element in $L$ that was requested twice or more since the last for $x$. By the contradiction assumption $y$ appears in front of $z$. Let $i'$ be the index of the
last request for x. Let \( r_{z_1} \) and \( r_{z_2} \) be the first and second requests for z after the i’th request (for x), respectively. (\( r_{z_1} \) and \( r_{z_2} \) exist by the definition of z). By the definition of y, y was requested at most once between the i’th and i-th requests (for x) and therefore, was requested at most once between \( r_{z_1} \) and \( r_{z_2} \). By the induction hypothesis for the request \( r_{z_2} \) and by the definitions of \( \text{MRU}(1) \) and \( \text{TMS} \) it must be that z passed y at that time (if z was not already in front of y).

It may be the case though that y was requested once after the second request for z (i.e. \( r_{z_2} \)) and before the current request for x (i.e. the i-th request). By the above derivation, it must be that just before such a request for y, z appears in front of y. We now prove that y will remain after z. By the induction hypothesis for this request for y and by the definitions of \( \text{MRU}(1) \) and \( \text{TMS} \) it cannot be that y will pass z since z must have been requested at least twice between this request for y and the previous one. Therefore, z must be in front of y and the invariant holds.

C Proof of Lemma 8

To see the first part of the lemma, we observe that the expected number of subsequent requests in a local set is

\[
\sum_{t=1}^{\infty} t \cdot \alpha^{t-1} \cdot (1 - \alpha).
\]

It is straightforward to verify that the value of this sum is \( 1/(1 - \alpha) \).

To show the second part of the lemma, we make use of a result from the theory of Markov chains. This result tells us that the stationary distribution of a Markov source with transition matrix \( P \) is the unique probability vector \((p_1, \ldots, p_m)\) satisfying

\[
(p_1, \ldots, p_m) \cdot P = (p_1, \ldots, p_m).
\]

We show that, if \( P \) is the transition matrix defined in equation (6) and the probability vector \((p_1, \ldots, p_m)\) is defined according to equation (7), condition (11) is satisfied which implies the second part of the lemma.

Let \((a_1, \ldots, a_m)\) be the vector resulting from the matrix multiplication on the left side of equation (11), i.e.

\[
(a_1, \ldots, a_m) := (p_1, \ldots, p_m) \cdot P
\]

\[
= \left( q_1 k, \ldots, q_n k, \cdots, q_1 k, \ldots, q_n k \right) \cdot \left( \begin{array}{cccc}
\alpha Q & \frac{1 - \alpha}{k+1} Q & \cdots & \frac{1 - \alpha}{k+1} Q \\
\frac{1 - \alpha}{k+1} Q & \alpha Q & \cdots & \frac{1 - \alpha}{k+1} Q \\
& \ddots & \ddots & \ddots \\
& & \frac{1 - \alpha}{k+1} Q & \frac{1 - \alpha}{k+1} Q & \cdots & \alpha Q
\end{array} \right).
\]

Remember that \( n = k \cdot m \) and that \( Q \) is the \((n \times n)\)-matrix with all lines identical to the vector \((q_1, \ldots, q_n)\). Because of the form of the matrix \( P \) and because the entries of \((p_1, \ldots, p_m)\) repeat with period \( n \), we can restrict our attention to the first \( n \) entries of \((a_1, \ldots, a_m)\) and the first \( n \) columns of \( P \). The entry \( a_j \) is the scale product of \((p_1, \ldots, p_m)\) and the \( j \)th column of \( P \), i.e.

\[
a_j = \sum_{\mu=1}^{n} \frac{q_\mu}{k} \cdot \alpha q_j + (k - 1) \sum_{\mu=1}^{n} \frac{q_\mu}{k} \cdot \frac{1 - \alpha}{k-1} q_j.
\]

The simplification of the right side yields

\[
a_j = \alpha \frac{q_j}{k} + (1 - \alpha) \frac{q_j}{k} = \frac{q_j}{k} = p_j.
\]

Thus \( a_j = p_j \) and the lemma follows immediately.
D Results of the access cost experiment

This section gives the detailed results of the access cost experiments we performed. The algorithms are ranked in terms of the ratio of the algorithms' cost and the cost of the algorithm that performed best among the examined algorithms. Additionally, each table gives the average access cost per request of the best algorithm. Thus, each algorithm’s average access cost can be computed as the product of its cost ratio and the average access cost of the best algorithm.

Table 4 gives the results of the access cost experiment on Zipf sequences with $m = 8, 16$ and 32 distinct items. The results of the Markov experiment are listed in Table 5 for the values $\alpha = 0.1, 0.5$ and 0.9. Finally, Tables 6 and 7 present the results obtained on the request sequences extracted from the Calgary Corpus.

<table>
<thead>
<tr>
<th>$m = 8$</th>
<th>Average access costs for FC:</th>
<th>$m = 16$</th>
<th>Average access costs for FC:</th>
<th>$m = 32$</th>
<th>Average access costs for FC:</th>
</tr>
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<tbody>
<tr>
<td>FC</td>
<td>1.00000</td>
<td>M(1)</td>
<td>1.15123</td>
<td>PR(3)</td>
<td>1.18213</td>
</tr>
<tr>
<td>FC'</td>
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<td>M(2)</td>
<td>1.15123</td>
<td>MR(0)</td>
<td>1.18888</td>
</tr>
<tr>
<td>TRANS</td>
<td>1.09800</td>
<td>M(2)</td>
<td>1.15154</td>
<td>MR(0)</td>
<td>1.18888</td>
</tr>
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<td>MF(2)</td>
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<td>M(2)</td>
<td>1.15129</td>
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<td>1.18924</td>
</tr>
<tr>
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<td>FR(2)</td>
<td>1.16100</td>
<td>MRF(4)</td>
<td>1.19339</td>
</tr>
<tr>
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<td>FR(2)</td>
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</tr>
<tr>
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<td>MR(3)</td>
<td>1.17592</td>
<td>MR(7)</td>
<td>1.20319</td>
</tr>
<tr>
<td>P(1)</td>
<td>1.15123</td>
<td>PR(3)</td>
<td>1.18213</td>
<td>MR(7)</td>
<td>1.20319</td>
</tr>
</tbody>
</table>

Table 4: Costs ratios on request sequences of length $10^6$ produced by distributions according to Zipf’s law.
Table 5: Costs ratios on request sequences of length $10^6$ produced by the Markov source of Section 7.3.1 for the values $\alpha = 0.1, 0.5$ and 0.9.

E Variable length prefix-free binary encodings

In the compression experiment, we examined various variable length prefix-free binary coding schemes. We now give short descriptions of some standard coding schemes. Then we explain the phasing technique which can often be applied to improve codeword sets. Finally, we give precise descriptions of the codeword sets used in our experiments.

Standard coding schemes

We start with four coding schemes providing an infinite number of codewords. Such coding schemes are used, if no upper bound on the number of codewords (or alternatively the integers to be encoded) is known.

**Elias encoding:** To encode the integer $i \geq 1$, we transmit the unary encoding of the length of the binary representation of $i$, followed by the binary representation of $i$ itself, excluding the most significant bit. Thus $i$ is encoded with $2 \lfloor \log_2 i \rfloor + 1$ bits.

**$\delta$-encoding:** For an integer $i \geq 1$, the length of the binary representation of $i$ is encoded by Elias
encoding, followed by the binary representation of \( i \) excluding the most significant bit. Thus \( i \) is encoded with \( 1 + \lfloor \log_2 i \rfloor + 2\lfloor \log_2(1 + \lfloor \log_2 i \rfloor) \rfloor \) bits.

**\( \omega \)-encoding:** To encode \( i \geq 1 \), the binary representation \( \beta(i) \) of \( i \) is written. Then the binary representation of \( [\beta(i)] - 1 \) is appended to the left. This process is repeated recursively and halts on the left with 2 bits. A single zero is appended on the right to mark the end of the codeword.

**\( \omega' \)-encoding:** This coding scheme is similar to the \( \omega \)-encoding, but halts with 3 bits.

If only a finite number of codewords is needed, coding schemes like the ones above are usually inefficient, and techniques like the following often yield better encodings.

**Start-step-stop-encodings:** The start-step-stop family produces a great variety of codes. Each member of the family is specified by three parameters \( a, b \) and \( c \). An \((a,b,c)\)-start-step-stop code uses \( k \) different binary encodings of lengths \( a, a + b, a + 2b, \ldots, a + c \). That is, it consists of \( k = (c-a)/b + 1 \) different binary codes. To indicate which binary code \( s \) with \( 1 \leq s \leq k \) is used, the codeword is prefixed by the unary representation of \( s \). Thus, an \((a,b,c)\)-code provides

\[
\sum_{i=0}^{(c-a)/b} 2^{a+i b} = \frac{2^{b+c} - 2^a}{2^b - 1}
\]

codewords.

**Phasing**

If only a finite number of codewords is needed, variable length prefix-free codes can often be improved by the so-called **phasing technique**.

If integers \( i \) with \( 1 \leq i \leq m \) are to be encoded, i.e. \( m \) codewords are needed, each integer can be encoded with \( k = \lfloor \log_2 m \rfloor \) bits. However if \( m < 2^k \), then \( 2^k - m \) codewords remain unused. In this case, the coding can be done in the following way. If \( i < 2^k - m \) then \( i \) is encoded in \( k - 1 \) bits by the binary representation of \( i - 1 \). If \( i > 2^k - m \), then \( i + 2^k - m \) is encoded in \( k \) bits by the binary representation of \( i - 1 + 2^k - m \).

Start-step-stop codes can often be improved by the phasing technique, if not all codewords in one of the binary subcodes are needed. The codes used in the compression experiment have been improved in this way.

**Codeword sets used in the compression experiment**

In the byte-level compression experiment of Section 8, we obtained the best results with a \((2,2,8)\)-start-step-stop code. By the above formula, this code provides 340 codewords, however only 257 are needed. Therefore, we applied the phasing technique on the last binary code of length 8, thus obtaining the codeword set described in Table 8. The colons in the codewords mark the ends of codeword prefixes and are not transmitted.

Positions in the 7-element space character list are encoded using a 2/3-bit binary encoding optimized by the phasing technique. To encode the 251 positions in the non-space list, we developed a special code described in Table 9 of Appendix E. The first 56 list positions are encoded by a \((3,1,5)\)-start-step-stop code. The remaining positions are encoded by the prefix 000 followed by an 8-bit binary representation again optimized by the phasing technique.
The word-level compression algorithm of Section 8 works with two word lists of arbitrary length. For these two lists, we therefore need coding schemes providing an infinite number of codewords. In the experiment, we use an Elias encoding to encode locations in the space word list and δ-encoding in the non-space word list. However, the two character lists have only finite length, and we developed special codeword sets for them. We use a simple 2/3-bit binary code improved by the phasing technique for the 7-element space character list. The non-space character list holds 251 characters, thus we need 251 codewords. The first 56 codewords are taken from a (3,1,5)-start-step-stop code. The remaining codewords are provided by a 7/8-bit binary code (improved by the phasing technique) where each codeword is prefixed by 000. The two character list codeword sets are given in Table 9.

F Results of the compression experiment

Tables 10 and 11 show the results of the compression experiment with the Bentley et al. scheme on byte- and word-level, respectively. The tables give the compression ratios, that is the number of produced output bits per input character, achieved on the files of the Calgary corpus. The algorithms appear ordered by their average compression ratio with respect to the entire corpus which is given in the last column.
Table 6: Costs ratios on request sequences extracted from file book1 of the Calgary Corpus.
Table 7: Costs ratios on request sequences extracted from file geo of the Calgary Corpus.
Table 8: The (2, 2, 8)-start-stop-stop code (optimized by the phasing technique) used in the byte-level compression experiment.

<table>
<thead>
<tr>
<th>pos.</th>
<th>codeword</th>
<th>length</th>
<th>pos.</th>
<th>codeword</th>
<th>length</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1:00</td>
<td>3</td>
<td>85</td>
<td>000:000000</td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>1:11</td>
<td>3</td>
<td>167</td>
<td>000:1010010</td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>01:0000</td>
<td>6</td>
<td>168</td>
<td>000:10100110</td>
<td>11</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>20</td>
<td>01:1111</td>
<td>6</td>
<td>256</td>
<td>000:11111110</td>
<td>11</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>21</td>
<td>001:000000</td>
<td>9</td>
<td>EOF</td>
<td>000:11111111</td>
<td>11</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>84</td>
<td>001:111111</td>
<td>9</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 9: The codes used to transmit list positions in the character lists of the word-level compression experiment.

<table>
<thead>
<tr>
<th>pos.</th>
<th>codeword</th>
<th>length</th>
<th>pos.</th>
<th>codeword</th>
<th>length</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>00</td>
<td>2</td>
<td>5</td>
<td>101</td>
<td>3</td>
</tr>
<tr>
<td>2</td>
<td>010</td>
<td>3</td>
<td>6</td>
<td>110</td>
<td>3</td>
</tr>
<tr>
<td>3</td>
<td>011</td>
<td>3</td>
<td>7</td>
<td>111</td>
<td>3</td>
</tr>
<tr>
<td>4</td>
<td>100</td>
<td>3</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>pos.</th>
<th>codeword</th>
<th>length</th>
<th>pos.</th>
<th>codeword</th>
<th>length</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1:000</td>
<td>4</td>
<td>57</td>
<td>000:0000000</td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>1:111</td>
<td>4</td>
<td>117</td>
<td>000:011100</td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>01:0000</td>
<td>6</td>
<td>118</td>
<td>000:01111010</td>
<td>11</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>24</td>
<td>01:1111</td>
<td>6</td>
<td>251</td>
<td>000:11111111</td>
<td>11</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>25</td>
<td>001:00000</td>
<td>8</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
<td></td>
<td>...</td>
<td></td>
</tr>
<tr>
<td>56</td>
<td>001:111111</td>
<td>8</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Table 10: Results of the byte-level compression experiment.