Topics last week

- Concurrent garbage collection:
  - Dijkstra,
  - DLG
Concurrent Garbage Collection
Platfrom in Mind

Strong machines (servers): Symmetric MultiProcessing (SMP) shared-memory, multiprocessor
Terminology

- **Informal Pause times**
  - 500ms
  - 50ms
  - 5ms

- **Stop-the-World**

- **Parallel**

- **Concurrent**

- **On-the-Fly**

- **Throughput Loss: 10%**

Throughput Loss: 10%
Next

• Mostly concurrent: IBM’s implementation
  • Mostly Concurrent collector improvements.
    ▪ An algorithmic approach
  • Endo & Taura’s idea on shortening pause times
  • If time allows:
    ▪ Snapshot copy-on-write
    ▪ Parallel GC
Mostly Concurrent Garbage Collection

[Boehm-Demers-Shenker 1991]
[Printezis-Detlefs 2000]
[Endo-Taura 2002]
[Barabash, Ben-Yitzhak, Goft, Kolodner, Leikehman, Ossia, Owshanko, Petrank 2005]
Recall Motivation

- Garbage collection costs:
  - Throughput
  - Pause lengths
- The goal: reduce pause times with a small reduction in throughput.
- Idea: run (most of the) collection concurrently with mutators.
Recall Difficulty

- The heap changes during collection.
- The main problem is that marked (black) objects may point to unmarked (white) objects.

- **Solution**: trace again all marked objects that were modified by the program.
- Use a card table to record modified objects (actually, cards).
Mostly-concurrent GC

- **Trace**: run marking concurrently.
  - Write barrier: when a pointer is modified, its card is marked.
- **Card cleaning**: for each dirty card:
  - Clear dirty bit
  - Re-trace from all marked objects on the card.
  - (Roots are scanned, assuming they are all on dirty cards.)
- **Stop mutators**
- **Repeat** card cleaning **while** program halted.
- **Resume mutators**
- **Sweep**.
More Issues

- New objects are created black (marked).
- Liveness: Objects unreachable in the beginning of the collection are guaranteed to be reclaimed.
- Floating garbage: Objects that become unreachable during the collection might not be collected.
- Trade-offs: It is possible to do more phases of card cleaning.
Conclusion

- This collector does most of the work concurrently with the program.
- It is stopped for a short while in the end to clear (and scan) all dirty cards.
- Properties:
  - Short pauses, simple write-barrier
  - Overhead: write barrier, repeated scanning of dirty cards.
Parallel, Incremental, and Mostly Concurrent GC

- A specific memory manager
- IBM Production JVM since ~2002
- Published in PLDI’02, OOPSLA’03, TOPLAS’05
Motivation (Industry Style)

- Modern SMP servers introduce
  - Higher level of true parallelism
  - Multi-gigabyte heaps
  - Multi-threaded applications which must ensure fast response time
- New demands from Garbage Collection (GC)
  - Short pause time on large heaps
    - Not “real-time”, but restricted below a given limit
  - Minimal throughput hit
  - Scalability on multi-processor hardware
  - Efficient algorithms for weak ordering hardware
    - We will not talk about this....
Mark-Sweep-Compact GC

- The collector is mark-sweep-compact.
- Mark - traces all reachable (live) objects in heap
- Sweep - Create a list of free chunks
- Compact
  - Move the live objects, to create bigger free chunks
  - Usually very long.
Bitwise Sweep

- A major overhead of sweep is finding & freeing each chunk of 0’s in the mark-bit table.

- **Solution:** free only large chunks of objects.
  - Sweep uses only full zero words (fast search).
  - When found – free the entire chunk of zeros (not only the space presented by the zero word).

- Advantage: looking for a zero **word** is fast.

- Disadvantage: looses some space (but only small chunks).
The General Picture

Mark

Sweep

Compact?

- Used
- Marked
- Free
- Dark matter
- Unmovable
The Concurrent Collection Costs

- Stop-the-world may get to seconds (at 2004)
- Cost of mark phase dominant
The Mostly Concurrent Collection

- Tracing done while mutator threads are active
- Mutator runs card marking: “dirties” cards that are modified.
- Card cleaning runs concurrently.
- Finally, a short stop-the-world phase
  - Last clean and resulting tracing
  - Sweep (or ever better, lazy sweep)
The Write Barrier and Object “cleaning” Solution

Tracer: Marks and traces

Java Mutator: Modifies Blue and Green objects
Write barrier on objects

Tracer: Traces rest of graph

Tracer: Clean blue object
Who Runs the Collection?

- Tracing done incrementally by the mutator threads, when allocating. (Recall Baker’s copying collector.)
- Incremental and parallel: several threads may run their incremental share of the collection in parallel.
- Finally, add some concurrency to the picture.
Incremental and parallel

Incremental, Concurrent and Parallel:
Phases of The Collector

- **Concurrent phase**
  - Reset the mark bits and the dirty cards table
  - Trace all reachable objects (incremental, parallel, concurrent).
  - Write Barrier records dirty cards in a card table
  - A single card cleaning pass: in each dirty card, retrace all marked objects

- **Final stop-the-world phase**
  - Root scanning and final card cleaning pass
  - Tracing of all additional objects
  - Parallel sweep (To be replaced by concurrent sweep).
Write Barrier Implementation

- Activated by the JVM, on each reference change done in Java.
- Cards are 512 bytes; card table has a bit for each card.
- Note that card cleaning may happen anytime
  - Including in the middle of write barrier execution!
- Therefore a race is possible…
Write Barrier Race

- A race between card cleaning and write barrier.
- Naïve write barrier:
  - Obj1.a = Obj2
    1. Set Obj1.a to Obj2
    2. Dirty the entry of Obj1 in the card table
- If collector finishes between 1 and 2, it will not see the dirty card!
- Switching order does not help since card cleaning can happen between 1 and 2, erasing the dirty mark.
Avoiding the Race

- Extra registration in a local variable.
- Obj1.a = Obj2
  1. Store Obj2 in a root (guaranteed to be reachable)
  2. Set Obj1.a to Obj2
  3. Dirty the entry of Obj1 in the card table
  4. Remove Obj2 from root
- This also solves sensitivity to memory coherence, not discussed in this course.
Outline

- Introduction
- Principles of concurrent collector
- **Dynamically controlling the concurrent work**
- Parallel load balancing mechanism
- Coding issues
- Results (highlights)
- Algorithmic Improvement
  - Results
The Problem of Punctual termination

- Stop-the-world collection starts when heap is full
- Mostly concurrent aims at completing the marking exactly when heap becomes full
  - Completing GC late - program gets stalled.
  - Completing GC early - we get more garbage collection cycles and pay an efficiency cost.
- Solution: adaptive incremental work.
Advantage of Incremental Work

- We can influence collection speed by choosing how much collection to do with each allocation.
- The ratio of collector work to program allocation is denoted by the *tracing rate*.
  - Tracing rate = work to do per allocated byte.
  - Goal: tracing rate = work-to-be-done/free-space.
  - Implies that tracing terminates on time.
- Estimate remaining work and free space, tune tracing rate.
Impact of Tracing Rate

- On a low tracing rate
  - GC takes a long time
  - Many cards get dirty
  - Repeated tracing takes more time
- GC is less efficient, program gets less CPU overall.
- But: program gets more CPU percentage.
- Therefore, we let the user specify an initial tracing rate.
- Start a collection when: estimated work on live objects > free×TR.
Behavior Patterns

Stop-The-World Mark-Sweep GC Throughput 100%

Mostly Concurrent (lower GC utilization) Throughput 80%

Most Concurrent (higher GC utilization) Throughput 90%

JVM Utilization and Performance with Mark-Sweep GC and Mostly Concurrent GC
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Load Balancing Goal

- Avoid idle time
- Efficient synchronization
- Simple termination detection.

- Small tasks $\rightarrow$ good load balancing
- Large tasks $\rightarrow$ low synchronization costs.
- Tasks = list of objects (pointers) to traverse.
Work Packets

- Separate mark-stack into smaller work packets.
- Obtain a packet using fine-grained synchronization (compare-and-swap)
- Group packets according to occupancy.
Work Packets

- Each thread keeps an input packets and an output packet.
- Pop an object from input work-packet.
- Mark children and push to output work-packet.
- An empty input packet is returned to the empty-packets pool.
- Try to obtain as full as possible new input packet.
- A full output packet is returned to the “full” pool.
- Get as empty as possible new output packet.
Advantages of WorkPackets

- Easy work distribution
- Packet size determines task size
- Simple detection of termination (all packets in empty list)
- Good performance in practice.
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Concurrent Code is Difficult to Write
Debug and Maintain

- Races between concurrent tracing and program
- Races between concurrent tracers
- Debug version cannot reproduce Release bugs
- Problems surface only occasionally
- Behavior is machine dependent
About 40% verification code

- Sanity checks
  - Asserts, consistency checks
  - Logging of collection activity, state, and history
    - Shadow heap, for tracing history
    - Shadow card table, for card state and treatment
    - Code to use the above for printing detailed information.
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Comparison with STW GC

- Compared to STW MSC
  - Using IBM's production level JVM
  - 4-way machines
  - NT, AIX and IA64
- Mostly testing SPECjbb
  - heap size: 60% live objects
- Pause time cut by 75%
- Mark time by 86%.
  - Sweep become dominant
- Throughput hit of 10%
Comparison with STW GC (cont.)

- Also testing pBOB
  - IBM internal benchmark
  - Fit for 2.5 GB heap, with
- Low CPU utilization
  - Many threads
  - Typical to modern server Apps.
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- Algorithmic Improvement
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Algorithm Revisited

- [Barabash-Ossia-Petrank 2003]
- Two simple algorithmic improvements.
The Repetitive Work Problem

- An observation:
  - Suppose a card is dirtied.
  - Reachable objects on this card are marked and traced by the collector.
  - All these objects are later traced again during card cleaning.
- Outcome: repeated tracing
- First Improvement: Don’t trace through dirty cards
Moreover …

- On typical benchmarks:
  - Specific “hot” objects get modified frequently.
  - (Almost) all hot objects reside on dirty cards.
  - They point to objects that become unreachable later.
  - Since we trace these hot objects twice, we increase work and floating garbage.
- Not tracing through dirty cards avoids this waste.
Method & Properties

- While tracing, do not scan an object on a dirty card.

- Advantages:
  - Less (repeated) tracing work
  - Reduced floating garbage
- Thus, substantial throughput improvements

- Disadvantage: increased pause time
Timing of Card Dirtying

- Observation: dirtying a card tells us that previous tracing does not suffice.
- Therefore: no need to dirty a card if nothing was traced on it.
- Second Improvement: Undirty cards with no traced objects
  - Undirtying by scanning cards
  - Undirtying by checking local allocation caches
Undirrying via Scanning

- Undirrying periodically on the whole card table
  - Uses a second “traced” card table.
  - The card is marked when first object on it is traced.
- During the scan: undirty any card with no traced objects
  - Very effective in undirrying cards (cuts cleaning by 65%)
  - Scan imposes a cost.
- Frequency is a parameter:
  - Frequent scans: increases chances of catching cards before their objects are traced, but increase overhead
Local Allocation Caches

- An allocation optimization used by various modern JVMs
- The idea: each program thread obtains an “allocation cache” on which it allocates small objects with no synchronization

- Benefits:
  - Reduced synchronization
  - Better locality
Undirtying via Local Allocation Caches

- Typically, newly allocated objects are immediately initialized, thus their cards are typically dirty.
- But new objects are usually not traced immediately after creation.
- Idea: delay tracing in allocation caches, unditry “after initialization”
- Collector: don’t allow tracing on allocation caches
  - if needed, record pointers to be traced later. This hardly ever happens
- Allocator: after finishing allocation on a local cache, undirtty all included pages.
- Cuts the amount of dirty cards by more than 35%, at (almost) no cost.
Undirdy Cards with No Traced Objects

- **Advantages**
  - Reduces the work on scanning dirty cards.
  - This reduces the final stop-the-world phase.
  - Thus, significant impact on pauses.

- **Disadvantages**
  - Time overhead.
Implementation and Tests

- Implementation on top of the mostly concurrent collector that is part of the IBM production JVM 1.4.0.
- Platforms: tested on both an IBM 6-way pSeries server and an IBM 4-way Netfinity server
- Benchmarks: the SPECjbb2000 benchmark and the SPECjvm98 benchmark suite
- Measurements: performance of the base mostly concurrent collector vs. the improved version
Results - Throughput Improvement

- SPECjbb. 6-way PPC. Heap size 448 MB
- 26.7% improvement (at tracing rate 1)
Results - Floating Garbage Reduction

- SPECjbb. 6-way PPC. Heap size 448 MB
- 13.4% improvement in heap residency (at tracing rate 1)
- Almost all floating garbage eliminated
Results - Pause Time Reduction

- SPECjbb. 6-way PPC. Heap size 448 MB
  - 33.3% improvement in average pause
  - 36.4% improvement in max pause
Conclusions

- Two improvements on the popular mostly concurrent algorithm
  - Reduce repetitive work (don’t trace through dirty cards)
  - Reduces number of dirty cards (undirty cards with no traced objects)
- Substantial improvement
  - Improved benchmark throughput by 26%
  - Almost eliminated floating garbage (heap residency reduced by 13%)
  - Reduced average pause time by 33%
Reducing Pause Times for the Mostly Concurrent Collector

Endo-Taura 2002
Reducing Pause Times

- Pause time is determined by the final stop-the-world phase in which cards are finally cleaned while the program is halted.

- Manage work to achieve short-pauses:
  - Limit the number of dirty cards
  - If the halt becomes long, let the program threads resume.
Limit the number of dirty cards

- If the number of dirty cards exceeds a predetermined threshold, immediately scan one card.
  - Advantage: limited number of cards will be scanned during the final phase.
  - Disadvantage: a card may be rescanned repeatedly a large number of time.
Stop a Halt

- If a halt scans too many objects, then go back to concurrent mode.
  - Advantage: Limited pause time.
  - Disadvantage: threads may exhaust heap before collection ends.
    - Triggering becomes more complicated.
Conclusion

- Ideas may be used to reduce the pause times considerably.
- Throughput may be harmed.
Conclusion – Mostly Concurrent

- Most of the work done concurrently with program.
- Program is stopped for a short while in the end to clear (and scan) all dirty cards.
- Properties:
  - Short pauses, simple write-barrier
  - Overhead: write barrier, repeated scanning of dirty cards.
- One of the most popular commercially
  - Used (at least by) IBM, SUN (Oracle), BEA.